

User's Manual

Model UT551 Digital Indicating Controller

User's Manual for Single-loop Control

IM 05D01C04-01E

GREEN SERIES

YOKOGAWA
Yokogawa Electric Corporation

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Introduction

Thank you for purchasing the UT551 digital indicating controller. The controller is shipped from the factory with 6 hardcopy user's manuals (A2 and A3 size) and 1 user's manual on CD-ROM. The 6 user's manuals in hardcopy format describe the operating procedures required for basic use (factory-set to single-loop control mode). It is recommended that you refer to these user's manuals to understand [1] installation, [2] initial settings, and [3] operating procedures of the controller. The CD-ROM contains an User's Manual (Reference) with descriptions of various functions and setting ranges that can be set as necessary. The manual also contains information on operations used to carry out control other than single-loop control. Moreover, the use of an optional parameter setting tool (Model: LL100-E10) allows you to easily perform settings and adjustments with a PC.

How to Use the Manuals

Purpose	Manual Title	Description	Media
Setup	Installation	Describes the tasks (installation, wiring, and others) required to make the controller ready for operations.	A2-size paper, back and front
Basic operation	Initial Settings	Describes examples of setting PV input types, control output types, and alarm types. Making settings described herein allows you to carry out basic control.	A2-size paper, back and front
Operating procedures and troubleshooting	Operations	Describes key operation sequences. For operation control through external contact inputs, see the back of Installation User's Manual.	A2-size paper, back and front
Brief operation	Parameter Map	Contains the parameter map used as a guideline for setting parameters.	A2-size paper, back and front
Function description and setpoint recording	Parameters	Briefly describes the functions of parameters. In addition, each parameter table has a User Setting column, where you can record your setpoints when setting them in the controller.	A2-size paper, back and front
Basic operation of Active Color PV Display	Setting / Explanation of Active Color PV Display	Describes the setting/explanation of Active Color PV Display.	A3-size paper, back and front
Detailed description of functions	User's Manual (Reference)	Explains more advanced applications than those found in the 6 hardcopy user's manuals (A2 and A3 size).	CD-ROM

1. Safety Precautions

The following symbol is indicated on the controller to ensure safe use.

CAUTION

This symbol on the controller indicates that the operator must refer to an explanation in the user's manual in order to avoid the risk of injury or death of personnel or damage to the instrument. The manual describes how the operator should exercise special care to avoid electric shock or other dangers that may result in injury or loss of life.

The following symbols are used in the hardcopy user's manuals and in the user's manual supplied on the CD-ROM.

NOTE

Indicates that operating the hardware or software in a particular manner may damage it or result in a system failure.

IMPORTANT

Draws attention to information that is essential for understanding the operation and/or features of the controller.

Exemption from Responsibility

Make sure that all of the precautions are strictly adhered to. Yokogawa Electric Corporation assumes no liability for any damage resulting from use of the instrument in contradiction to the precautions. Also, Yokogawa Electric Corporation assumes no liability to any party for any loss or damage, direct or indirect, caused by the use or any unpredictable defect of the instrument.

Regarding Protection, Safety, and Prohibition Against Unauthorized Modification

- (1) In order to protect the product and the system controlled by it against damage and ensure its safe use, make certain that all of the instructions and precautions relating to safety contained in this document are strictly adhered to. Yokogawa does not guarantee safety if products are not handled according to these instructions.
- (2) Modification of the product is strictly prohibited.

2. Model and Suffix Codes

Before using the controller, check that the model and suffix codes match your order.

Model	Suffix Code	Description
UT551		Digital indicating controller (provided with retransmission output and 15 VDC loop power supply as standard)
Type	-0	Standard type
	-1	Position proportional type
	-2	Heating/cooling type
	-3	Standard type (with 24 V DC loop power supply)
	-4	Position proportional type (with 24 V DC loop power supply)
Optional functions	0	None
	1	With communication, auxiliary analog (remote) input, 6 additional DIs and 4 additional DOs
	2	With communication, auxiliary analog (remote) input, and 1 additional DI
	3	With 5 additional DIs and 4 additional DOs
	4	With auxiliary analog (remote) input and 1 additional DI

Check that the following items are provided:

- Digital indicating controller (of ordered model): 1
- Brackets (mounting hardware): 1 pair
- Unit label: 1
- User's Manuals for Single-loop Control: 5 (A2 size)
- User's Manuals "Setting/Explanation of Active Color PV Display": 1 (A3 size)
- User's Manual (Reference) (CD-ROM Version): 1

Correspondence between the Model and Suffix Codes, and the Contact Input/Output Terminals Provided

Check the model ordered and the presence/absence of contact inputs and outputs in the following table.

✓ indicate that the contacts are available.

Model and Suffix Codes	Contact input terminals								Contact output terminals						
	DI1	DI2	DI3	DI4	DI5	DI6	DI7	DI8	DO1	DO2	DO3	DO4	DO5	DO6	DO7
UT551-□0	✓	✓							✓	✓	✓	✓	✓	✓	✓
UT551-□1	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
UT551-□2	✓	✓							✓	✓	✓	✓	✓	✓	✓
UT551-□3	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
UT551-□4	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓

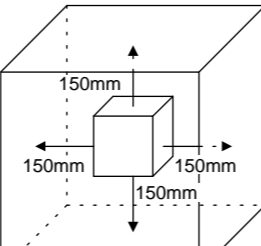
Note: For details on the functions of contact inputs/outputs, see "Terminal Wiring Diagrams" on the back of the manual.

3. How to Install

NOTE

To install the controller, select a location where:

- (1) no one may accidentally touch the terminals,
- (2) mechanical vibrations are minimal,
- (3) corrosive gas is minimal,
- (4) temperature can be maintained at about 23°C and the fluctuation is minimal,
- (5) no direct radiant heat is present,
- (6) no magnetic disturbances are caused,
- (7) no wind blows against the terminal board (reference junction compensation element),
- (8) no water is splashed,
- (9) no flammable materials are around,

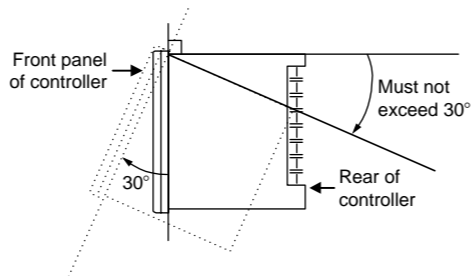


Never place the controller directly on flammable items or equipment.

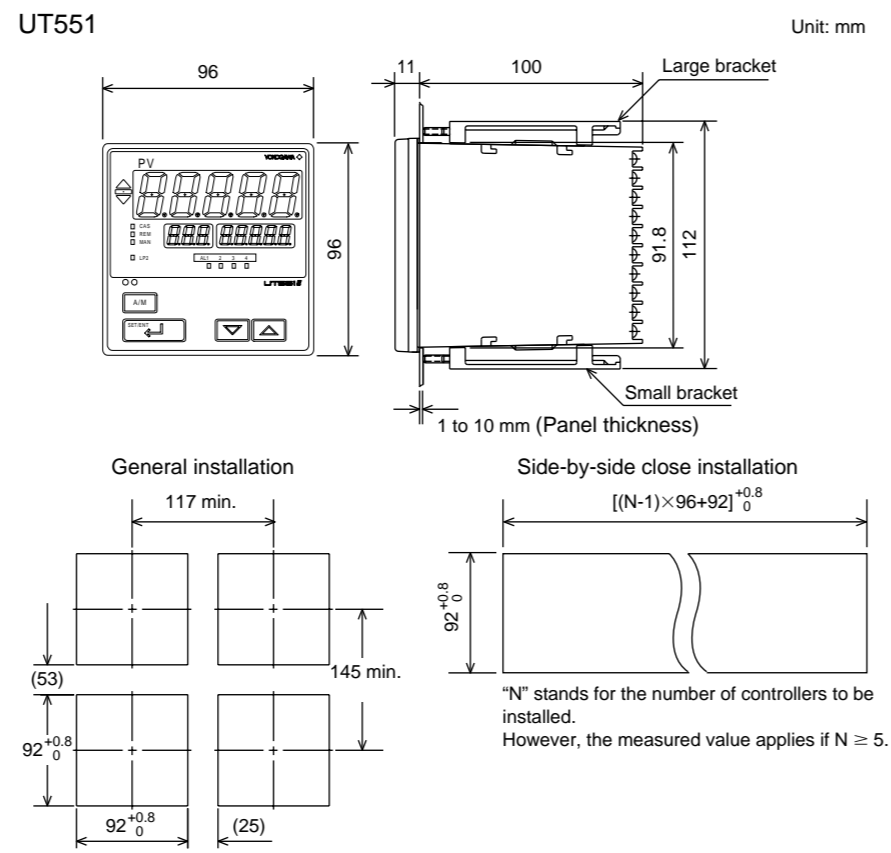
If the controller has to be installed close to flammable items or equipment, be sure to provide shielding panels all around the controller, at least 150mm away from every side; the panels should be made of either 1.43mm-thick metal-plated steel plates or 1.6mm-thick uncoated steel plates.

Installation Position

Install the controller at an angle within 30° from horizontal with the front panel facing upward. Do not install it facing downward. The position of right and left sides should be horizontal.



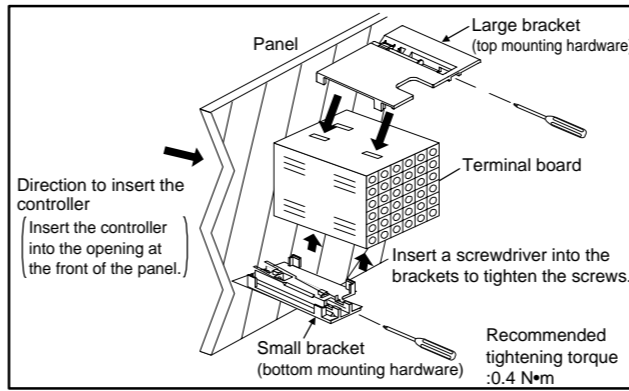
External Dimensions and Panel Cutout Dimensions



How to Install

CAUTION

Turn off the power to the controller before installing it on the panel because there is a possibility of electric shock.



- After opening the mounting hole on the panel, follow the procedures below to install the controller:
1. Insert the controller into the opening from the front of the panel so that the terminal board on the rear is at the far side.
 2. Set the brackets in place on the top and bottom of the controller as shown in the figure on the left, then tighten the screws of the brackets. Take care not to overtighten them.

4. How to Connect Wires

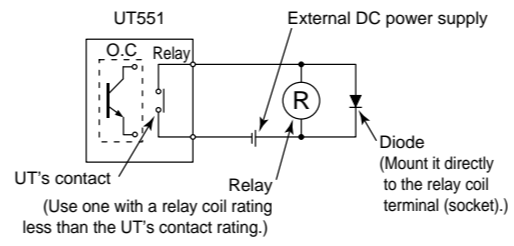
CAUTION

- 1) Before carrying out wiring, turn off the power to the controller and check that the cables to be connected are not alive with a tester or the like because there is a possibility of electric shock.
- 2) For the protection and safe use of the controller, be sure to place a circuit breaker (conforms with IEC60947, 5A, 100V or 220V AC) near the controller where the breaker can easily be operated. In addition, be sure to indicate that it is the instrument to cut the power supply of the controller.
- 3) Wiring must be carried out by personnel who have basic electrical knowledge and practical experience.

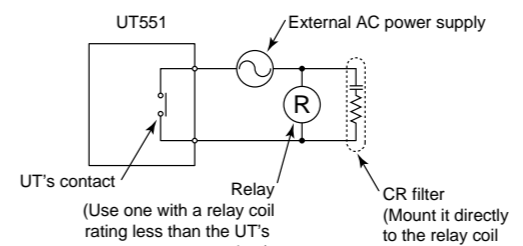
NOTE

- 1) Provide power from a single-phase instrument power supply. If there is a lot of noise in the power line, insert an insulating transformer into the primary side of the line and use a line filter (recommended part: ZAC2205-00U from TDK) on the secondary side. As a countermeasure against noise, do not place the primary and secondary power cables close to each other.
- 2) For the thermocouple input, use shielded compensating lead wires for wiring. For RTD input, use shielded wires that have low conductor resistance and cause no significant differences in resistance between the three wires. The cables to be used for wiring, terminal specifications, and recommended parts are as shown below.
- 3) Control output relays may be replaced. However, because they have a life of 100,000 times that of the resistance load, use auxiliary relays to turn on/off a load.
- 4) The use of inductance (L) loads such as auxiliary relays, motors and solenoid valves causes malfunction or relay failure; always insert a CR filter for use with alternating current or a diode for use with direct current, as a spark-removal surge suppression circuit, into the line in parallel with the load.
- 5) When there is possibility of being struck by external lightning surge, use the arrester to protect the instrument.

For DC Relay Wiring



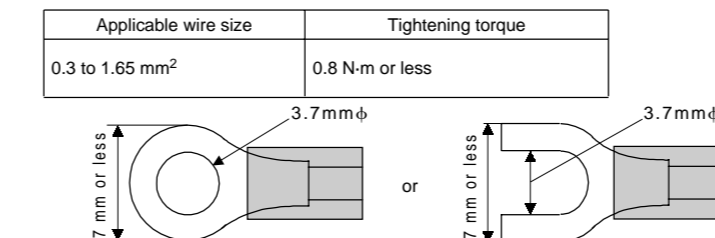
For AC Relay Wiring



Cable Specifications and Recommended Cables

Purpose	Name and Manufacturer
Power supply, grounding, relay contact outputs	600 V PVC insulated wires, JIS C 3307, 0.9 to 2.0 mm ²
Thermocouple	Shielded compensating leadwires, JIS C 1610, □X-□□-□□ (See Yokogawa Electric's GS 6B1U1-E.)
RTD	Shielded wires (three conductors), UL2482 (Hitachi Cable)
Other signals	Shielded wires

Recommended Terminal Lugs



Terminal Covers (Optional parts)

Target Model	Part Number	Sales Unit
For UT551	T9115YD	1

5. Hardware Specifications

PV Input Signals

- Number of inputs: 1 (terminals ①-③)
- Input type: Universal input system. The input type can be selected with the software.
- Sampling period: Can be selected from 50, 100, 200 and 500 ms.
- Burnout detection: TC, RTD, standard signal
- Functions at 0.4 to 2 V or 1 to 5 V Upscale, downscale, and off can be specified. For standard signal, burnout is determined to have occurred if it is 0.1 V or less.
- Input bias current: 0.05 μA (for TC or RTD b-terminal)
- Measurement current (RTD): About 0.13 mA
- Input resistance: 1 MΩ or more for thermocouple or mV input About 1 MΩ for DC voltage input
- Allowable signal source resistance: 250 Ω or less for thermocouple or mV input Effects of signal source resistance: 0.1 μV/Ω or less 2 kΩ or less for DC voltage input Effects of signal source resistance: About 0.01%/100 Ω
- Allowable wiring resistance: for RTD input Maximum 150 Ω/wire; Conductor resistance between three wires should be equal However, 10 Ω/wire for a maximum range of -150.0 to 150.0°C. Wire resistance effect: ±0.1°C/10 Ω
- Allowable input voltage: ±10 V DC for thermocouple, mV, or RTD input ±20 V DC for DC voltage input
- Noise rejection ratio: 40 dB (50/60 Hz) or more in normal mode 120 dB (50/60 Hz) or more in common mode
- Reference junction compensation error: ±1.0°C (15 to 35°C) ±1.5°C (0 to 15°C, 35 to 50°C)
- Applicable standards: JIS, IEC, DIN (ITS-90) for thermocouples and RTD

Remote Input Signals

- Available only for controllers with remote input terminals
- Number of inputs: 1 (terminals ④-⑥)
- Input type: Settable in a range of 0-2, 0-10, 0.4-2.0, or 1-5 V DC
- Sampling period: 100, 200 and 500 ms
- The sampling period of a remote input signal is associated with the PV input's sampling period. If the PV input's sampling period is 50 ms, however, the sampling period of a remote input signal lengthens to 100 ms.
- Input resistance: About 1 MΩ
- Input accuracy: ±0.3% ±1 digit of input span for 0 to 2 V DC ±0.2% ±1 digit of input span for 0 to 10 V DC ±0.375% ±1 digit of input span for 0.4 to 2.0 V DC ±0.3% ±1 digit of input span for 1 to 5 V DC Under standard operating conditions (23 ±2°C, 55 ±10% RH, power frequency of 50/60 Hz)

Feedback Resistance Input

- Provided for position proportional type only (terminals ⑦-⑨)
- Slide resistance value: 100 Ω to 2.5 kΩ of overall resistance (burnout detection for sliding wire provided)
- Measuring resolution: ±0.1% of overall resistance

Loop Power Supply

- Power is supplied to a two-wire transmitter. (15 V DC: terminals ⑩-⑪; 24 V DC: terminals ⑫-⑬)
- A resistor (10 to 250 Ω) connected between the controller and transmitter converts a current signal into a voltage signal, which is then read via the PV input terminal.
- Supply voltage: 14.5 to 18.0 V DC, max. 21 mA (provided with a protection circuit against a field short-circuit); 21.6 to 28.0 V DC, max. 30 mA (only for models with 24 V DC loop power supply)

Retransmission Output

- Either PV, target setpoint, or control output is output. Either the retransmission output or the 15V DC loop power supply can be used with terminals ⑭-⑯.
- Number of outputs: 1 or 2 (terminals ⑭-⑯, terminals ⑰-⑱)
- Output signal: 4-20, 0-20, 20-4, or 20-0 mA DC (where, outputting signal levels of less than 0 mA is not feasible)
- Load resistance: 600 Ω or less
- Output accuracy: ±0.1% of span (±5% of span for 1 mA or less.) under standard operating conditions (23 ±2°C, 55 ±10% RH, power frequency of 50/60 Hz)

Control Output

- Universal output system. The output type can be selected with the software.
- Relay contact output(s) for the position proportional type
- Current output (Standard type: terminals ⑲-⑳; heating-side output: terminals ㉑-㉒, cooling-side output: terminals ㉓-㉔)

Number of outputs	1 or 2 (two for heating/cooling type), switched between a voltage pulse output and current output.
Output signal	4-20, 0-20, 20-4, or 20-0 mA DC
Load resistance	600 Ω or less
Output accuracy	±0.1% of span (±5% of span for 1 mA or less) Under standard operating conditions (23 ±2°C, 55 ±10% RH, power frequency of 50/60 Hz)

- Voltage pulse output (Standard type: terminals ㉕-㉖; heating-side output: terminals ㉗-㉘, cooling-side output: terminals ㉙-㉚)

Number of outputs	1 or 2 (two for heating/cooling type), switched between a voltage pulse output and current output.
Output signal	On-voltage = 12 V or more (load resistance: 600 Ω or more) Off-voltage = 0.1 V DC or less
Resolution	10 ms or 0.1% of output, whichever is larger

- Relay contact output (Standard type: terminals ㉛-㉜; heating-side output: terminals ㉝-㉞, cooling-side output: terminals ㉟-㊱; position proportional type: terminals ㊲-㊳)

Number of outputs	1 or 2 points (two for heating/cooling type)
Output signal	Three terminals (NC, NO, and common)
Contact rating	250 V AC or 30 V DC, 3 A (resistance load)
Resolution	10 ms or 0.1% of output, whichever is larger

Contact Inputs

- Purpose: Target setpoint selection, remote/local mode switching, and run/stop switching
- Number of inputs: Differs with model and suffix codes as shown in the table below.

Model and Suffix Codes	Number of Inputs
UT551-□0	2
UT551-□1	8
UT551-□2	3
UT551-□3	7
UT551-□4	3

- Input type: Non-voltage contact or transistor open collector input
- Input contact rating: 12 V DC, 10 mA or more
- On/off determination: For non-voltage contact input, contact resistance of 1 kΩ or less is determined as "on" and contact resistance of 20 kΩ or more as "off." For transistor open collector input, input voltage of 2 V or less is determined as "on" and leakage current must not exceed 100 μA when "off."
- Minimum status detection hold time: PV input's sampling period × 3

Contact Outputs

- Purpose: Alarm output, FAIL output, and others
- Number of outputs: Differs with the model and suffix code as shown in the table below.

Model and Suffix Codes	Number of Outputs
UT551-□0	3
UT551-□1	7
UT551-□2	3
UT551-□3	7
UT551-□4	3

- Relay contact rating: 240 V AC, 1 A, or 30 V DC, 1 A
- Transistor contact rating: 24 V DC, 50 mA

Display Specifications

- PV display: 5-digit, 7-segment, red LEDs, character height of 20 mm
- Setpoint display: 3-digit and 5-digit, 7-segment, red LEDs, character height of 9.3 mm
- Status indicating lamps: LEDs

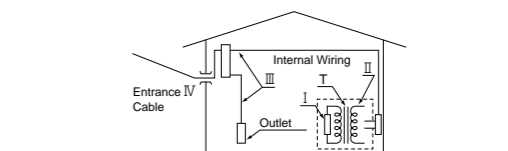
Safety and EMC Standards

- Safety: Complies with IEC/EN61010-1 (CE), approved by C22.2 No.61010-1, approved by UL508. Installation category : CAT. II Pollution degree : 2 (IEC/EN61010-1, C22.2 No.61010-1) Measurement category : I (CAT. I : IEC/EN61010-1) Rated measurement input voltage : 10V DC max.(across terminals), 300V AC max.(across ground) Rated transient overvoltage : 1500V (Note) Note : It is a value on the safety standard which is assumed by IEC/EN61010-1 in Measurement category I, and is not the value which guarantees an apparatus performance.

CAUTION

This equipment has Measurement category I, therefore do not use the equipment for measurements within Measurement categories II, III and IV.

Measurement category	Description	Remarks
I	CAT. I For measurements performed on circuits not directly connected to MAINS.	
II	CAT. II For measurements performed on circuits directly connected to the low voltage installation.	Appliances, portable equipments, etc.
III	CAT. III For measurements performed in the building installation.	Distribution board, circuit breaker, etc.
IV	CAT. IV For measurements performed at the source of the low-voltage installation.	Overhead wire, cable systems, etc.

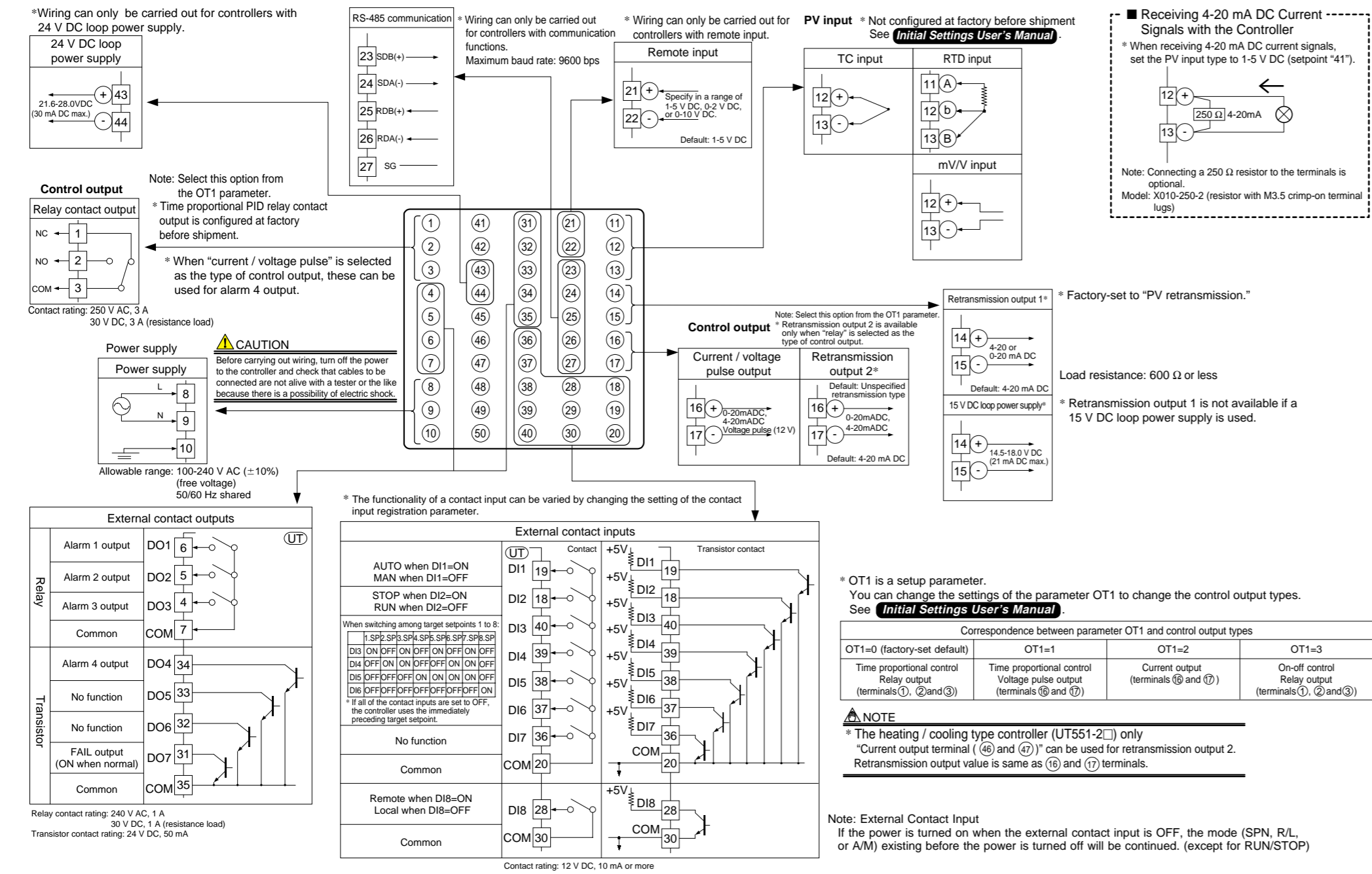


- EMC standards: Complies with EN61326, EN61000-3-2, EN61000-3-3 and EN55011 (CE), AS/NZS 2064 compliant (C-Track), Class A Group 1. The instrument continues to operate at a measuring accuracy of within ±20% of the range during tests.

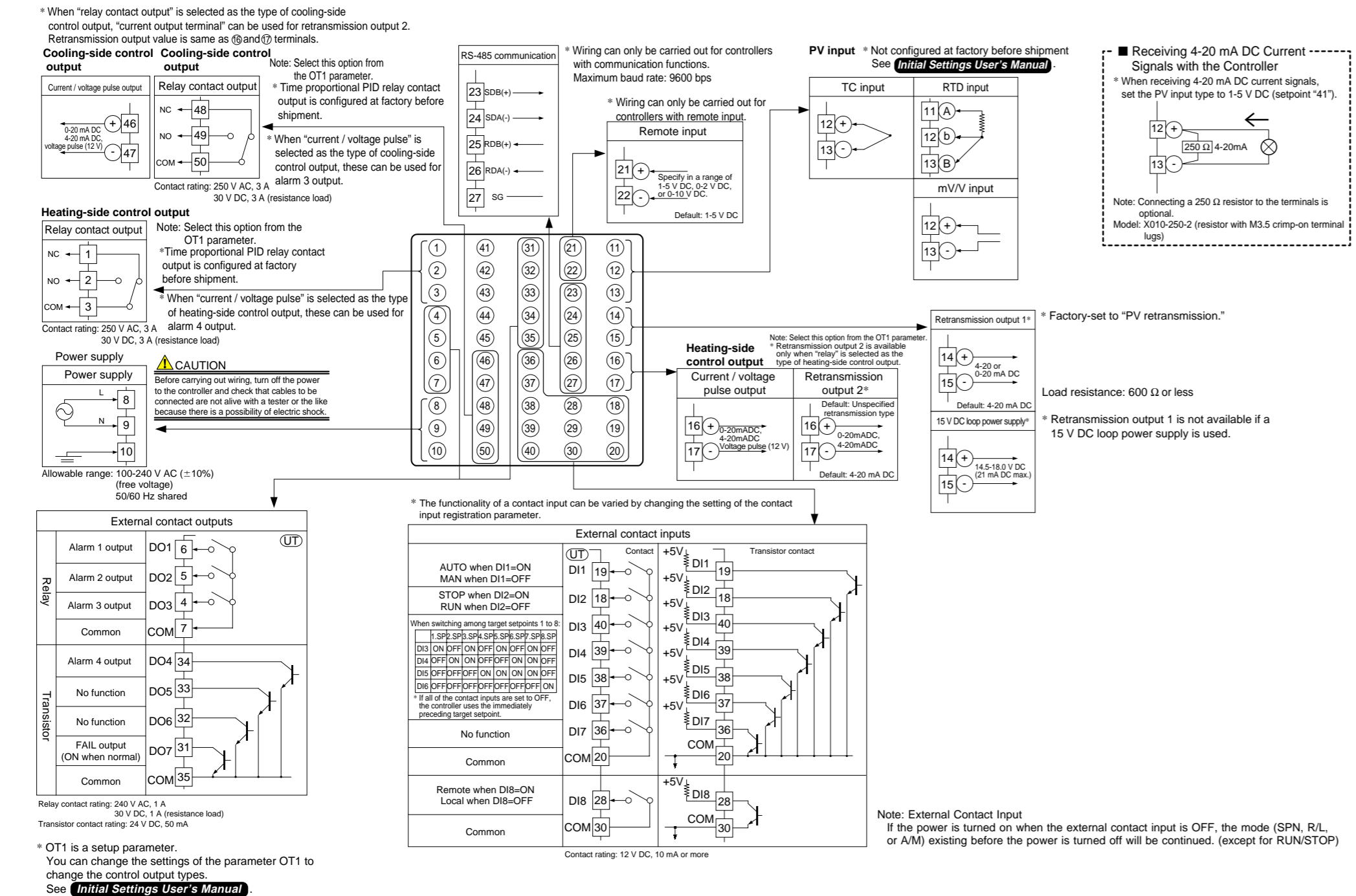
6. Terminal Wiring Diagrams

NOTE
Do not use unassigned terminals as relay terminals.

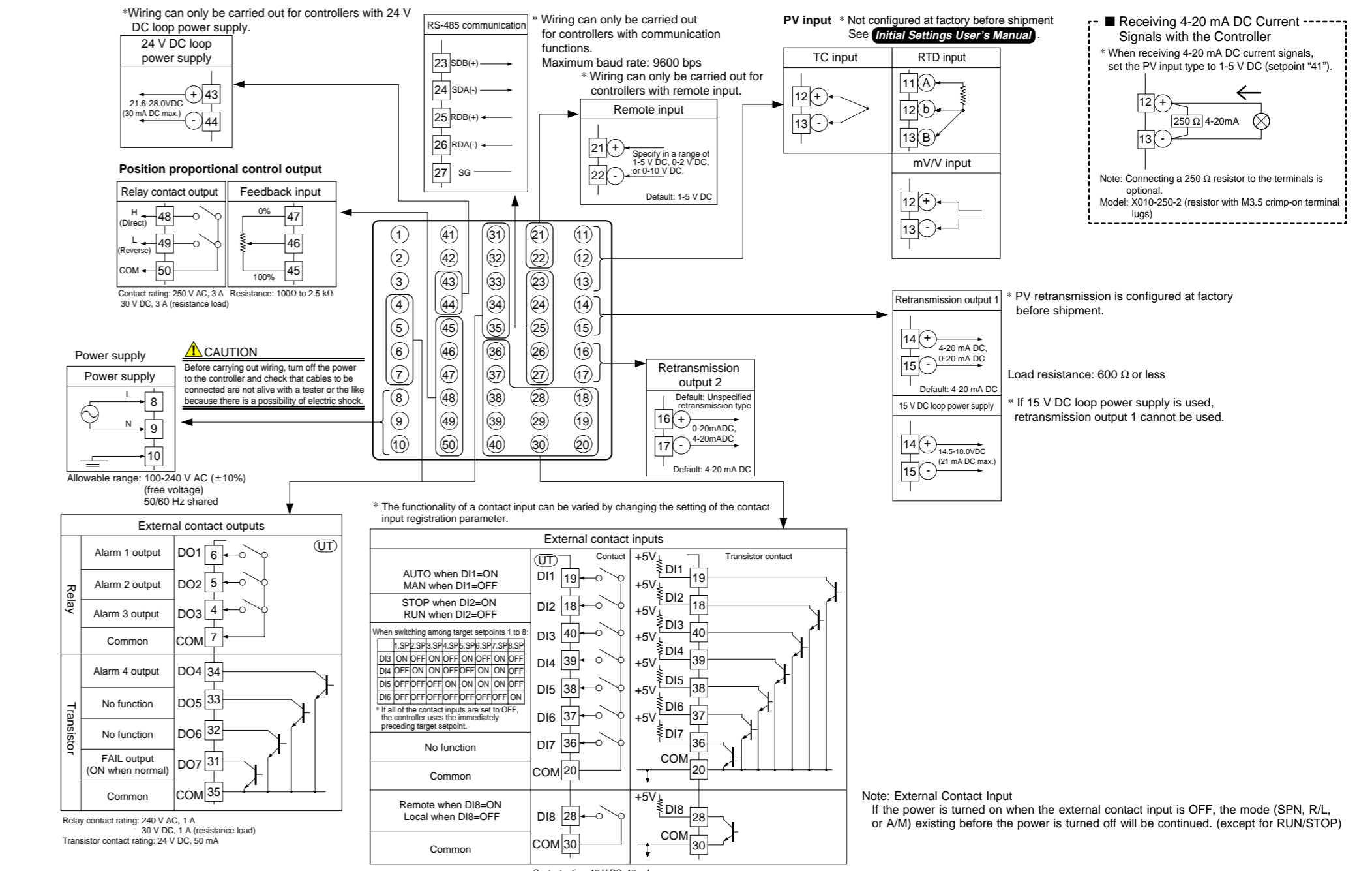
UT551 Standard Type (Model UT551-0□ or UT551-3□), or Heating/Cooling Type (Model UT551-2□), Single-loop Control



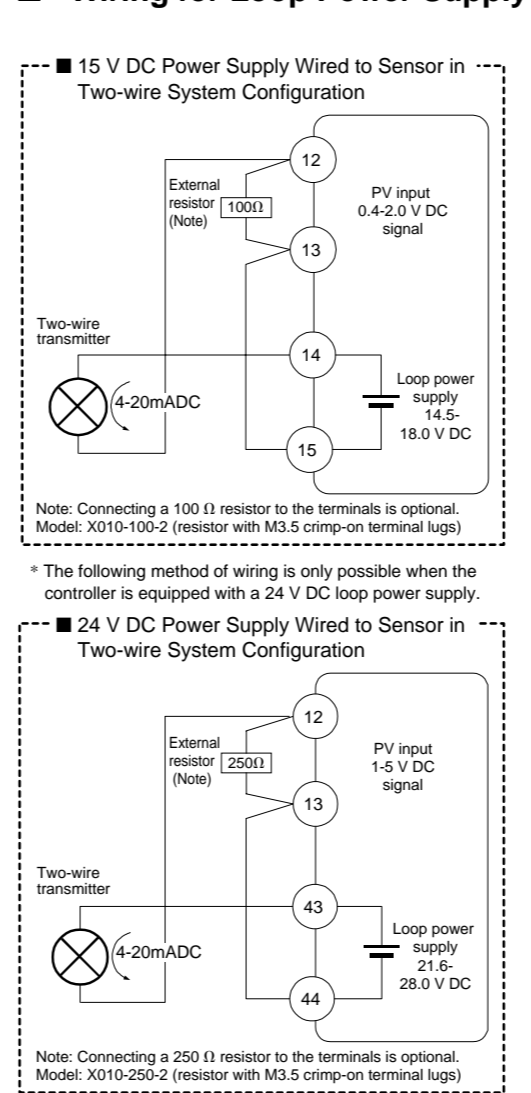
UT551 Heating/Cooling Type (Model UT551-2□), Single-loop Heating/Cooling Control



UT551 Position Proportional Type (Model UT551-1□ or UT551-4□), Single-loop Position Proportional Control



Wiring for Loop Power Supply

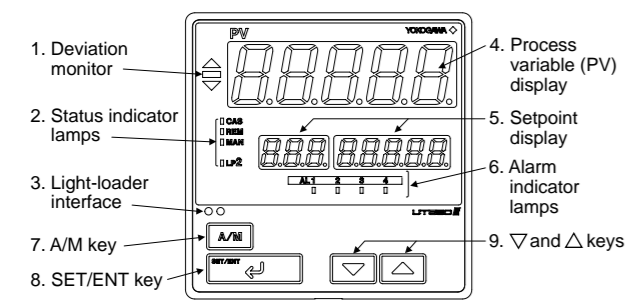


This manual describes examples of setting PV input types, control output types, and alarm types. Carrying out settings described herein allows you to perform basic control. Refer to examples of various settings to understand how to set parameters required. Refer to **Parameter Map User's Manual** for an easy to understand explanation of setting various parameters. If you cannot remember how to carry out an operation during setting, press the **SET/ENT** key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on.

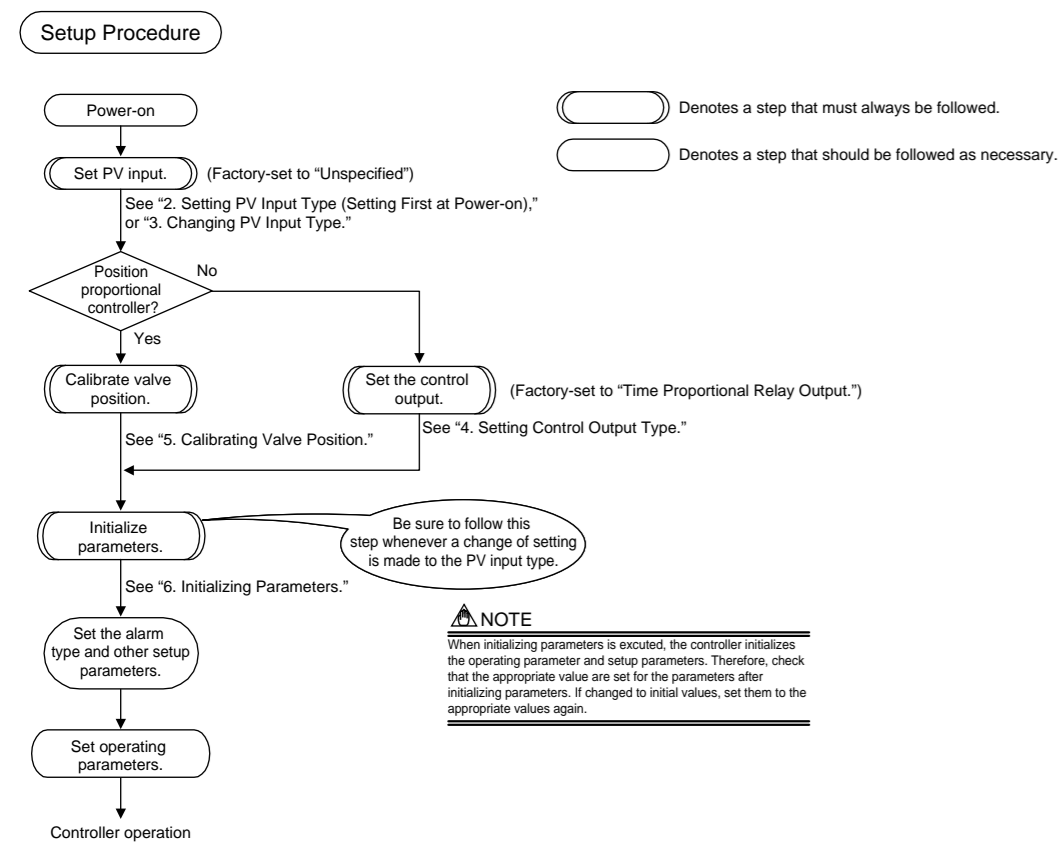
Contents

- Names and Functions of Front Panel Parts
- Setting PV Input Type (Setting First at Power-on)
- Changing PV Input Type
- Setting Control Output Type (Except for a Position Proportional Controller)
- Calibrating Valve Position (for a Position Proportional Controller Only)
- Initializing Parameters
- Changing Alarm Type
- Description of Multiple Setpoints and PID

1. Names and Functions of Front Panel Parts



Name of Part	Function
1. Deviation monitor	When lit, indicates the status of a deviation (PV - SP). △ : Is lit (in orange) if a deviation exceeds the deviation display range. □ : Is lit (in green) when a deviation is within the deviation display range. ▽ : Is lit (in orange) if a deviation falls below the deviation display range. The deviation monitor goes off if any display other than the operating display or SELECT display is shown.
2. Status indicator lamps	Is lit (in green) to indicate the status of operation or control. CAS: Not used in single-loop control. REM: Is lit when in remote mode. MAN: Is lit when in manual mode. LP2: Not used in single-loop control.
3. Light-loader interface	Interface for an adapter cable used when setting and storing parameters from a PC. This requires an optional parameter setting tool.
4. Process variable (PV) display	Displays PV. Displays an error code (in red or green) if an error occurs. Display color can be switched between red and green according to the setting of "PCM" setup parameter.
5. Setpoint display	Displays a parameter symbol in 3-digit LED. Displays the setpoint of a parameter in 5-digit LED.
6. Alarm indicator lamps	If any of alarms 1 to 4 occurs, the respective alarm indicator lamp (AL1 to AL4) is lit (in orange).
7. A/M key	Used to switch between the AUTO and MAN modes. Each time you press the key, it switches to the AUTO or MAN mode alternately.
8. SET/ENT key	Used to switch or register a parameter. Pressing the key for more than 3 seconds allows you to switch between the operating display and the main menu for operating parameter setting display alternately.
9. ∇ and ∆ keys	Used to change numerical values. On setting displays for various parameters, you can change target setpoints, parameters, and output values (in manual operation). Pressing the ∇ key decreases a numerical value, while pressing the ∆ key causes it to increase. You can hold down a key to gradually increase the speed of change. To change from the parameter setting (operating or setup) display to the menu or from the setup parameter setting display menu to operating parameter setting display menu, press the ∇ and ∆ keys simultaneously.



NOTE
 When initializing parameters is executed, the controller initializes the operating parameter and setup parameters. Therefore, check that the appropriate values are set for the parameters after initializing parameters. If changed to initial values, set them to the appropriate values again.

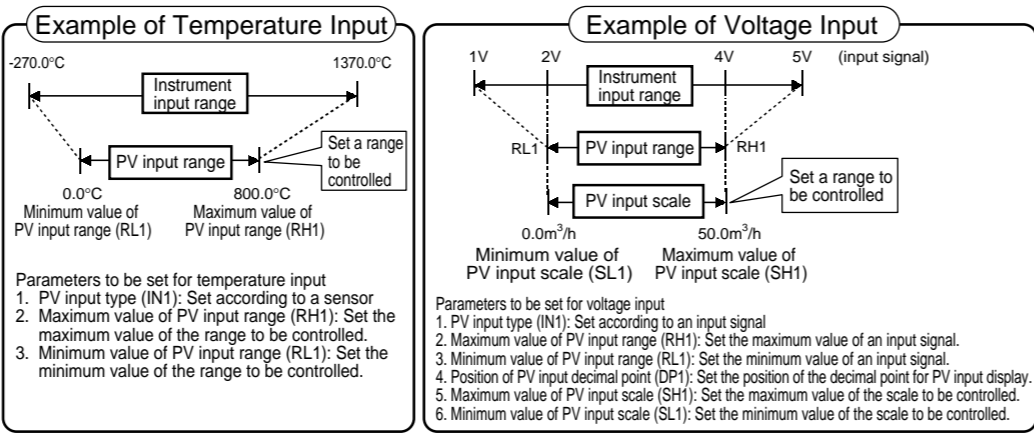
Setting of Main Parameters at the Factory before Shipment

Item	Factory-shipped values for standard type controllers	Factory-shipped values for heating/cooling type controllers	Factory-shipped values for position proportional type controllers
Remote input signal (only for controllers with remote inputs)	1 to 5 V DC (variable)		
Control output	Time proportional PID relay output (variable)	Heating side: Time proportional PID relay output (variable) Cooling side: Time proportional PID relay output (variable)	Relay output (fixed)
Control action	Reverse action (variable)	Not specified	
PID parameter	P = 5.0%, I = 240 seconds, D = 60 seconds.		
Alarm output	Alarm-1: PV high limit, Alarm-2: PV low limit, Alarm-3: PV high limit, Alarm-4: PV low limit		

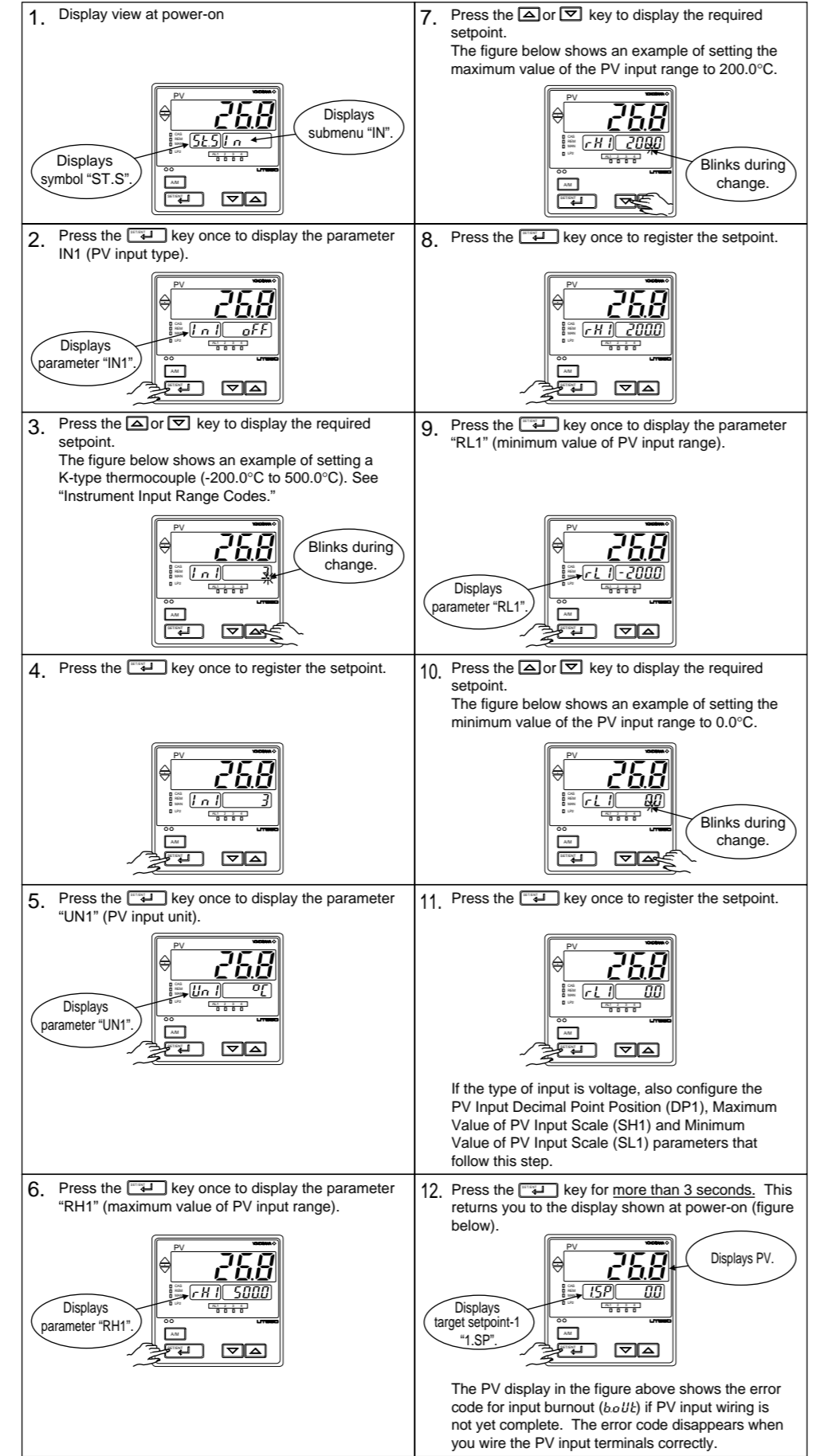
2. Setting PV Input Type (Setting First at Power-on)

NOTE

- The controller displays an operating display when the power is turned on. The submenu "IN" appears at this point if the type of PV input has not been defined yet. In this case, first press the **SET/ENT** key once to display the parameter "IN1" for the PV input type, and use the **∆** key to display the input range code to use, then press the **∇** key to register it. Then, set the maximum value (RH1) and minimum value (RL1) of the PV input range (for voltage input, set the maximum value (SH1) and minimum value (SL1) of the PV input scale). See the operating procedure below for more details.
- The controller is configured to the default of each parameter at the factory before shipment. First check these defaults listed in **Parameters User's Manual**, and change their values if necessary.



The following operating procedure describes an example of setting a K-type thermocouple (-200.0 to 500.0°C) and a measurement range of 0.0 to 200.0°C.



Instrument Input Range Codes

Input	Type	Instrument Input Range Code	Instrument Input Range	Measurement Accuracy			
Unspecified		OFF	Set the data item PV input type "IN1" to the OFF option to leave the PV input type undefined.				
Thermocouple	K	1	-270.0 to 1370.0°C -450.0 to 2500.0°F	±0.1% of instrument range ±1 digit at 0°C or more ±0.2% ±1 digit for temperatures below 0°C, where the accuracy is: ±2% of instrument range ±1 digit for temperatures below -200.0°C for a type-K thermocouple, or ±1% of instrument range ±1 digit for temperatures below -200.0°C for a type-T thermocouple.			
		2	-270.0 to 1000.0°C -450.0 to 2300.0°F				
		3	-200.0 to 500.0°C -300.0 to 1000.0°F				
		4	-200.0 to 1200.0°C -300.0 to 2300.0°F				
		5	-270.0 to 400.0°C -450.0 to 750.0°F				
		6	0.0 to 400.0°C -200.0 to 750.0°F				
		7	0.0 to 1800.0°C 32 to 3300°F				
		8	0.0 to 1700.0°C 32 to 3100°F				
		9	0.0 to 1700.0°C 32 to 3100°F				
RTD	P100	10	-200.0 to 1300.0°C -300.0 to 2400.0°F	±0.1% of instrument range ±1 digit ±0.25% of instrument range ±1 digit for temperatures below 0°C			
		11	-270.0 to 1000.0°C -450.0 to 1800.0°F				
		12	-200.0 to 900.0°C -300.0 to 1600.0°F				
		13	-200.0 to 400.0°C -300.0 to 750.0°F				
		14	0.0 to 400.0°C -200.0 to 1000.0°F				
		15	0.0 to 2300.0°C 32 to 4200°F				
		16	0.0 to 1390.0°C 32 to 2500.0°F				
		17	0.0 to 1800.0°C 32 to 3400°F				
		18	0.0 to 2000.0°C 32 to 3600°F				
		30	-200.0 to 500.0°C -300.0 to 1000.0°F		±0.1% of instrument range ±1 digit (Note1) (Note2)		
		31	-150.00 to 150.00°C -200.0 to 300.0°F				
		35	-200.0 to 850.0°C -300.0 to 1560.0°F		±0.1% of instrument range ±1 digit (Note1) (Note2)		
		36	-200.0 to 500.0°C -300.0 to 1000.0°F				
		37	-150.00 to 150.00°C -200.0 to 300.0°F				
		Standard signal	0.4 to 2 V		40	0.400 to 2.000 V	±0.1% of instrument range ±1 digit Display range is scalable in a range of -19999 to 30000. Display span is 30000 or less.
		1 to 5 V	41		1.000 to 5.000 V		
		0 to 2 V	50		0.000 to 2.000 V		
		0 to 10 V	51		0.00 to 10.00 V		
-10 to 20 mV	55	-10.00 to 20.00 mV					
0 to 100 mV	56	0.0 to 100.0 mV					

* Performance in the standard operating conditions (at 23±2°C, 55±10%RH, and 50/60 Hz power frequency)
 Note1: The accuracy is ±0.3°C of instrument range ±1 digit for a temperature range from 0°C to 100°C.
 Note2: The accuracy is ±0.5°C of instrument range ±1 digit for a temperature range from -100°C to 200°C.
 * To receive a 4-20 mA DC signal, select a standard signal of 1 to 5 V DC and connect it to a 250Ω resistor. This resistor is optional.
 Model: X010-250-2 (resistor with M3.5 crimp-on terminal lugs)

NOTE

The controller may automatically initialize the registered operating parameter setpoints if any change is made to the data item PV Input Type (IN1), Maximum Value of PV Input Range (RH1), Minimum Value of PV Input Range (RL1), PV Input Decimal Point Position (DP1), Maximum Value of PV Input Scale (SH1) or Minimum Value of PV Input Scale (SL1). After a change has been made to any of these data items, be sure to verify the registered operating parameter setpoints to ensure that they are correct. If any data item has been changed to its default, set it to a required value.

How to return to a menu
 Simultaneously press both the **∇** and **∆** keys once during parameter setting. This lets you return to the parameter menu.

Ranges Selectable for PV Input

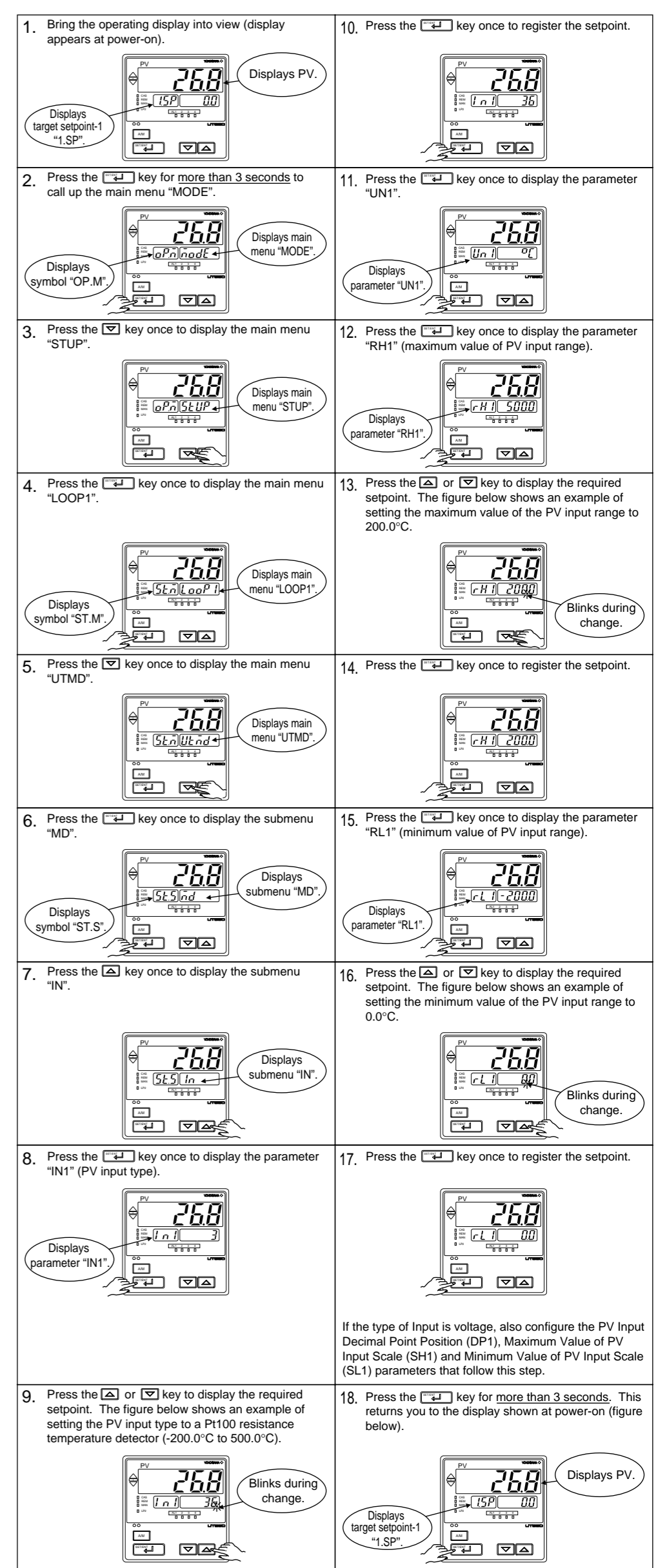
Thermocouple	1 to 18
RTD	30, 31, 35 to 37
DC voltage(mV,V)	40, 41, 50, 51, 55, 56

Ranges Selectable for Remote Input

DC voltage(V)	40, 41, 50, 51
---------------	----------------

3. Changing PV Input Type

The following operating procedure describes an example of changing the setting of K-type thermocouple (-200.0 to 500.0°C) to RTD Pt100 (-200.0 to 500.0°C) and a measurement range of 0.0 to 200.0°C.



If the type of Input is voltage, also configure the PV Input Decimal Point Position (DP1), Maximum Value of PV Input Scale (SH1) and Minimum Value of PV Input Scale (SL1) parameters that follow this step.

4. Setting Control Output Type (Except for a Position Proportional Controller)

The following operating procedure describes an example of changing time proportional PID relay output (0: factory-shipped value) to current output (2).

Control output terminal Values in parentheses are setpoints
 Time proportional PID relay (0)/on-off(3) output..... ①-②-③
 Current PID (2)/time proportional PID voltage pulse (1) output..... ④-⑦
 For details on the output terminals for heating/cooling control, see "6. Terminal Wiring Diagrams" in the **Installation User's Manual**.

- Bring the operating display into view (display appears at power-on). Displays PV.
- Press the key for more than 3 seconds to call up the main menu "MODE". Displays main menu "MODE".
- Press the key once to display the main menu "STUP". Displays main menu "STUP".
- Press the key once to display the main menu "LOOP1". Displays main menu "LOOP1".
- Press the key once to display the main menu "UTMD". Displays main menu "UTMD".
- Press the key once to display the submenu "MD". Displays submenu "MD".
- Press the key twice to display the submenu "OUT". Displays submenu "OUT".
- Press the key once to display the parameter "OT1" (control output type). Displays parameter "OT1".
- Press the or key to display the required setpoint. The figure below shows an example of setting to current output (4 to 20 mA DC). Displays parameter "OT1".
- Press the key once to register the setpoint. Blinks during change.

List of Control Output Types

Parameter Symbol	Name of Parameter	Setpoint	Control Output Types	
ot1 (OT1)	Control output type	0	Time proportional PID relay contact output (terminals ①-②-③)	
		1	Time proportional PID voltage pulse output (terminals ④-⑦)	
		2	Current output (terminals ④-⑦)	
		3	On/off control relay contact output (terminals ①-②-③)	
		The following 4 to 12 are displayed only for heating/cooling type controllers.		
		4	Heating-side relay output (terminals ①-②-③), cooling-side relay output (terminals ④-⑤-⑥)	
		5	Heating-side pulse output (terminals ④-⑦), cooling-side relay output (terminals ④-⑤-⑥)	
		6	Heating-side current output (terminals ④-⑦), cooling-side relay output (terminals ④-⑤-⑥)	
		7	Heating-side relay output (terminals ①-②-③), cooling-side pulse output (terminals ④-⑦)	
		8	Heating-side pulse output (terminals ④-⑦), cooling-side pulse output (terminals ④-⑦)	
		9	Heating-side current output (terminals ④-⑦), cooling-side pulse output (terminals ④-⑦)	
		10	Heating-side relay output (terminals ①-②-③), cooling-side current output (terminals ④-⑦)	
11	Heating-side pulse output (terminals ④-⑦), cooling-side current output (terminals ④-⑦)			
12	Heating-side current output (terminals ④-⑦), cooling-side current output (terminals ④-⑦)			

5. Calibrating Valve Position (for a Position Proportional Controller Only)

The following operation describes a procedure of inputting a feedback signal from a control valve to calibrate the full closed and full open positions of the valve automatically. To calibrate the valve position, you need to carry out wire connections and bring the controller into manual mode. For connections, see "6. Terminal Wiring Diagrams" in the **Installation User's Manual** and for entering the manual mode, see "8. Switching between AUTO and MAN" in **Operations User's Manual**.

- Bring the operating display into view (display appears at power-on). Displays PV.
- Press the key for more than 3 seconds to call up the main menu "MODE". Displays main menu "MODE".
- Press the key once to display the main menu "STUP". Displays main menu "STUP".
- Press the key once to display the main menu "LOOP1". Displays main menu "LOOP1".
- Press the key once to display the main menu "UTMD". Displays main menu "UTMD".
- Press the key once to display the submenu "MD". Displays submenu "MD".
- Press the key three times to display the submenu "VALV". Displays submenu "VALV".
- Press the key once to display the parameter "VAT". Displays parameter "VAT".
- Press the key to display "ON". Blinks during change.
- Press the key once. The controller automatically calibrates the valve position (fully open or closed). Blinks during change.
- The controller is viewed as shown below when the valve position is being automatically calibrated. The indication "ON" blinks.
- Calibration has ended successfully when the indication changes from "ON" to "OFF". Go to step [14]. Displays PV.
- Calibration has ended unsuccessfully if the indication changes from "ON" to "ERR". Check the feedback input wiring and carry out automatic calibration again. Displays "ERR".
- Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below). Displays PV.

6. Initializing Parameters

Be sure to follow the steps below after a change of setting has been made to the data item PV Input Type, PV Input Range or PV Input Scale.

CAUTION

Initializing the above parameter setpoints may initialize the registered operating/setup parameter setpoints. Check that they are correct. If any of them has been changed to its initial value, set it to a required value.

- Bring the operating display into view (display appears at power-on). Displays PV.
- Press the key for more than 3 seconds to call up the main menu "MODE". Displays main menu "MODE".
- Press the key once to display the main menu "STUP". Displays main menu "STUP".
- Press the key once to display the main menu "LOOP1". Displays main menu "LOOP1".
- Press the key once to display the main menu "UTMD". Displays main menu "UTMD".
- Press the key once to display the submenu "MD". Displays submenu "MD".

- Press the key twice to display the submenu "INIT". Displays submenu "INIT".
- Press the key once to display the parameter "INI". Displays parameter "INI".
- Press the key to display "ON". Blinks during change.
- Press the key once to display the main menu "LOOP1". Displays main menu "LOOP1".
- Press the key once to display the submenu "SP". Displays submenu "SP".
- Press the key once to display the submenu "ALM". Displays submenu "ALM".
- Press the key once. The display momentarily becomes blank (which is normal), indicating the parameters have been initialized. Displays PV.
- Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below). Displays PV.

7. Changing Alarm Type

The following operating procedure describes an example of changing alarm 1 (factory-set to the PV high limit alarm) to the PV low limit alarm. When you have changed alarm type, the alarm setpoint will be initialized; set the alarm setpoint again.

- Bring the operating display into view (display appears at power-on). Displays PV.
- Press the key for more than 3 seconds to call up the main menu "MODE". Displays main menu "MODE".
- Press the key once to display the main menu "STUP". Displays main menu "STUP".
- Press the key once to display the main menu "LOOP1". Displays main menu "LOOP1".
- Press the key once to display the submenu "SP". Displays submenu "SP".
- Press the key once to display the submenu "ALM". Displays submenu "ALM".
- Press the key twice to display the parameter "AL1" (alarm-1 type). Displays parameter "AL1".
- Press the or key to display the required setpoint. The figure below shows an example of setting the PV low limit alarm. Blinks during change.
- Press the key once to register the setpoint. You can take the same steps for alarm-2 type (AL2), alarm-3 type (AL3), and alarm-4 type (AL4) that are displayed after this.
- Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below). Displays PV.
- When setting alarm setpoints, see "5. Setting Alarm Setpoints" in **Operations User's Manual**.

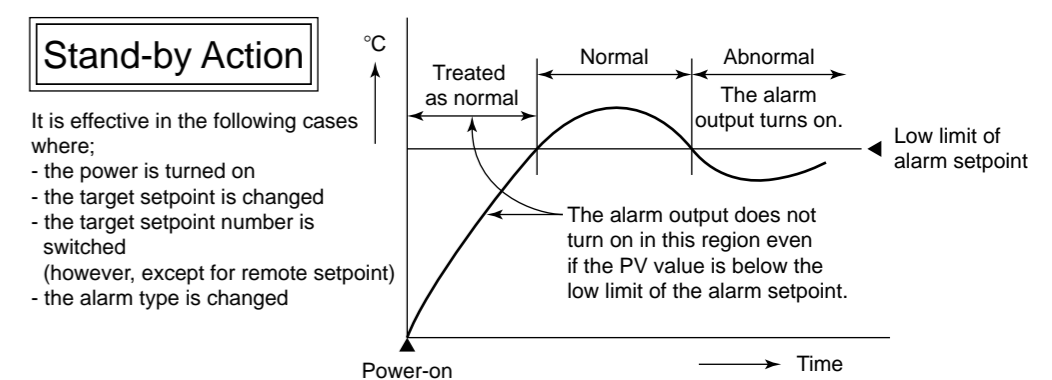
List of Alarm Types

The table below shows the alarm types and alarm actions. In the table, codes 11 to 10 and 33 to 38 are not provided with stand-by actions, while codes 11 to 20 and 43 to 48 are provided with stand-by actions.

Alarm type	Alarm action	Alarm type code	Alarm type	Alarm action	Alarm type code
No alarm	OFF	0	Hysteresis		
PV high limit	Open (unit) / Closed (lit) / Alarm setpoint	1	De-energized on deviation low limit alarm (Note 3)	Open (lit) / Closed (unit) / Deviation setpoint / SP	6
PV low limit	Closed (lit) / Open (unit) / Alarm setpoint / PV	2	De-energized on PV high limit	Closed (lit) / Open (unit) / Alarm setpoint / PV	7
Deviation high limit (Note 3)	Open (unit) / Closed (lit) / Deviation setpoint / PV / SP	3	De-energized on PV low limit	Closed (unit) / Open (lit) / Alarm setpoint / PV	8
Deviation low limit (Note 3)	Closed (lit) / Open (unit) / Deviation setpoint / PV / SP	4	Sensor grounding alarm	Sensor grounding alarm	9
De-energized on deviation high limit alarm (Note 3)	Closed (lit) / Open (lit) / Deviation setpoint / PV / SP	5	Fault diagnosis output (Note1)	FAIL output (Note2)	10
Upward (hour/minute)		21	Timer function (control stability report event) (Alarm-1 only)	Upward (minute/second)	25
Downward (hour/minute)		22	Upward (minute/second)	Downward (minute/second)	26
Upward (minute/second)		23	SP high limit	Open (unit) / Closed (lit) / Alarm setpoint	27
Downward (minute/second)		24	SP low limit	Closed (lit) / Open (unit) / Alarm setpoint / Output value	28
SP high limit	Open (unit) / Closed (lit) / Alarm setpoint	28	Deviation high limit for target setpoint (Note 3)	Open (unit) / Closed (lit) / Deviation setpoint / Target SP	29
SP low limit	Closed (lit) / Open (unit) / Alarm setpoint / SP	29	Deviation low limit for target setpoint (Note 3)	Closed (lit) / Open (unit) / Deviation setpoint / Target SP	30
Deviation high limit for target setpoint (Note 3)	Open (unit) / Closed (lit) / Deviation setpoint / Target SP	33	De-energized on deviation high limit alarm for target setpoint (Note 3)	Open (lit) / Closed (unit) / Deviation setpoint / Target SP	31
Deviation low limit for target setpoint (Note 3)	Closed (lit) / Open (unit) / Deviation setpoint / Target SP	34	De-energized on deviation low limit alarm for target setpoint (Note 3)	Closed (unit) / Open (lit) / Deviation setpoint / Target SP	36
De-energized on deviation high limit alarm for target setpoint (Note 3)	Closed (unit) / Open (lit) / Deviation setpoint / Target SP	35	De-energized on deviation low limit alarm for target setpoint (Note 3)	Closed (unit) / Open (lit) / Deviation setpoint / Target SP	43
De-energized on deviation low limit alarm for target setpoint (Note 3)	Closed (unit) / Open (lit) / Deviation setpoint / Target SP	36	De-energized on deviation high limit alarm for target setpoint (Note 3)	Open (unit) / Closed (lit) / Deviation setpoint / Target SP	44
De-energized on deviation high limit alarm for target setpoint (Note 3)	Open (unit) / Closed (lit) / Deviation setpoint / Target SP	37	De-energized on deviation low limit alarm for target setpoint (Note 3)	Closed (unit) / Open (lit) / Deviation setpoint / Target SP	47
De-energized on deviation low limit alarm for target setpoint (Note 3)	Closed (unit) / Open (lit) / Deviation setpoint / Target SP	38	De-energized on deviation high limit alarm for target setpoint (Note 3)	Open (unit) / Closed (lit) / Deviation setpoint / Target SP	48

Note 1: The fault diagnosis output turns on in case of input burnout, A/D converter failure, or reference junction compensation (RJC) failure. For input burnout or A/D converter failure, the control output is set to the setpoint of the Preset Output Value operating parameter (PO).

Note 2: The FAIL output is on during normal operation and turns off in case of failure.
 Note 3: The difference of alarm action between the alarm type codes 3 to 8, 13 to 18 and 33 to 38, 43 to 48 in the table above is as follows. The codes 3 to 8, 13 to 18 are effective for current setpoints. (For example, they are effective for the ramp rate setpoint at SP switching.) The codes 33 to 38, 43 to 48 are effective for target setpoints. (For example, they are not effective for the ramp rate setpoint at SP switching.)



8. Description of Multiple Setpoints and PID

The UT551 has a maximum of eight target setpoints, and has PID for each of these setpoints. The following shows the correspondence between the target setpoint numbers (SPN), target setpoints (SP), and PID parameters. However, when the setup parameter ZON (zone PID selection parameter) = 0. For example, if you have set "2" to the target setpoint number (SPN), the control parameters available are target setpoint (2.SP), proportional band (heating-side proportional band) (2.P), integral time (heating-side integral time) (2.I), derivative time (heating-side derivative time) (2.D), cooling-side proportional band (2.Pc), cooling-side integral time (2.Ic), and cooling-side derivative time (2.Dc). To use multiple target setpoints, see the table below to check the corresponding parameters.

Target setpoint number (SPN)	Target setpoint (SP)	PID parameter					
		Proportional band (heating-side proportional band)	Integral time (heating-side integral time)	Derivative time (heating-side derivative time)	Cooling-side proportional band	Cooling-side integral time	Cooling-side derivative time
SPN=1	1.SP	1.P	1.I	1.D	1.Pc	1.Ic	1.Dc
SPN=2	2.SP	2.P	2.I	2.D	2.Pc	2.Ic	2.Dc
SPN=3	3.SP	3.P	3.I	3.D	3.Pc	3.Ic	3.Dc
SPN=4	4.SP	4.P	4.I	4.D	4.Pc	4.Ic	4.Dc
SPN=5	5.SP	5.P	5.I	5.D	5.Pc	5.Ic	5.Dc
SPN=6	6.SP	6.P	6.I	6.D	6.Pc	6.Ic	6.Dc
SPN=7	7.SP	7.P	7.I	7.D	7.Pc	7.Ic	7.Dc
SPN=8	8.SP	8.P	8.I	8.D	8.Pc	8.Ic	8.Dc

This manual describes key entries for operating the controller. For operations using external contact inputs, see "6. Terminal Wiring Diagrams" in **Installation User's Manual**. If you cannot remember how to carry out an operation during setting, press the \square key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on.

Contents

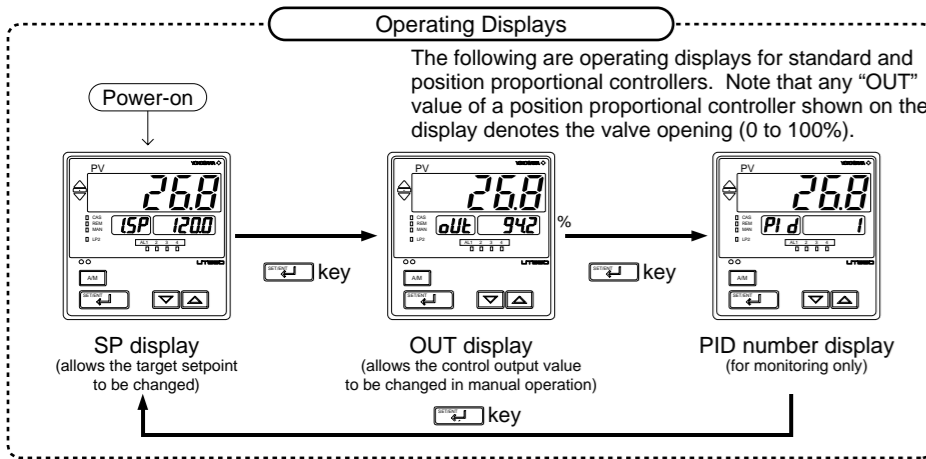
1. Monitoring-purpose Operating Displays Available during Operation
2. Setting Target Setpoint (SP)
3. Performing/Canceling Auto-tuning
4. Setting PID Manually
5. Setting Alarm Setpoints
6. Selecting Target Setpoint Numbers (SPN)
7. Switching between Run and Stop
8. Switching between AUTO and MAN
9. Manipulating Control Output during Manual Operation
10. Switching between Remote (REM) and Local (LCL)
11. Troubleshooting

1. Monitoring-purpose Operating Displays Available during Operation

The monitoring-purpose operating displays available during operation are roughly classified into two groups depending on the types of controller and control output. One group is operating displays for standard and position proportional controllers and the other group is operating displays for a heating/cooling controller.

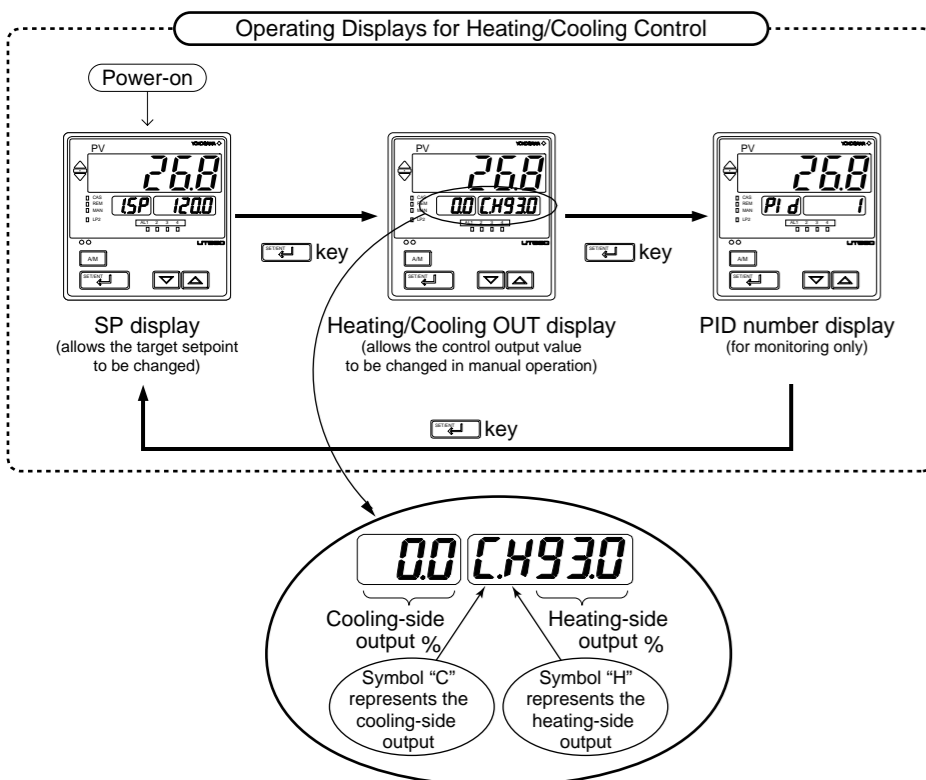
Operating Displays for Standard and Position Proportional Controllers

- **SP Display**
The PV input value appears on the PV display. The target setpoint (1.SP) appears on the Setpoint display. (can be changed)
- **OUT Display**
The PV input value appears on the PV display. The control output value (OUT) appears on the Setpoint display. (can be changed in manual operation)
- **PID Number Display**
The PV input value appears on the PV display. The PID number (PID) being used appears on the Setpoint display.



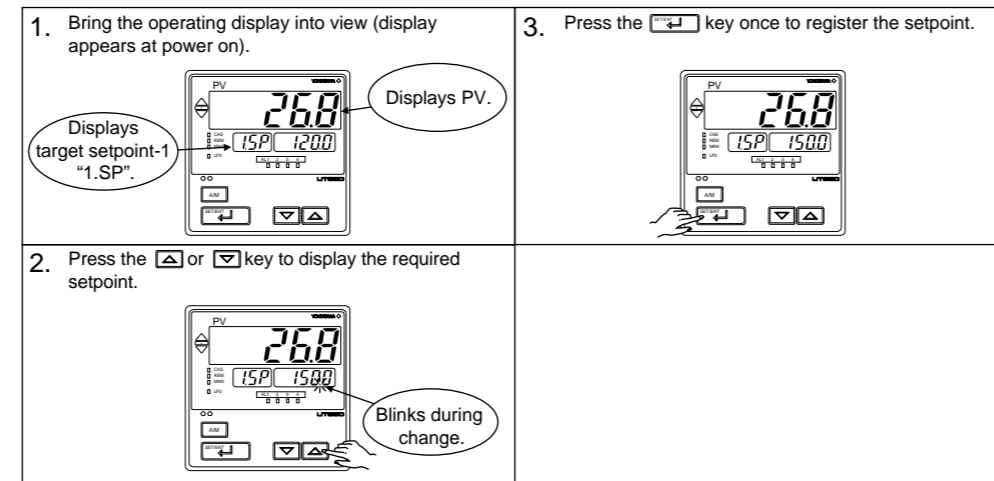
Operating Displays for a Heating/Cooling Controller

- **SP Display**
The PV input value appears on the PV display. The target setpoint (1.SP) appears on the Setpoint display. (can be changed)
- **Heating/Cooling OUT Display**
The PV input value appears on the PV display. The heating and cooling sides control output value (C.H) appears on the Setpoint display. (can be changed in manual operation)
- **PID Number Display**
The PV input value appears on the PV display. The PID number (PID) being used appears on the Setpoint display.



2. Setting Target Setpoint (SP)

The following operating procedure describes an example of setting 150.0 to a target setpoint. In automatic operation, the controller starts control using set target setpoints.

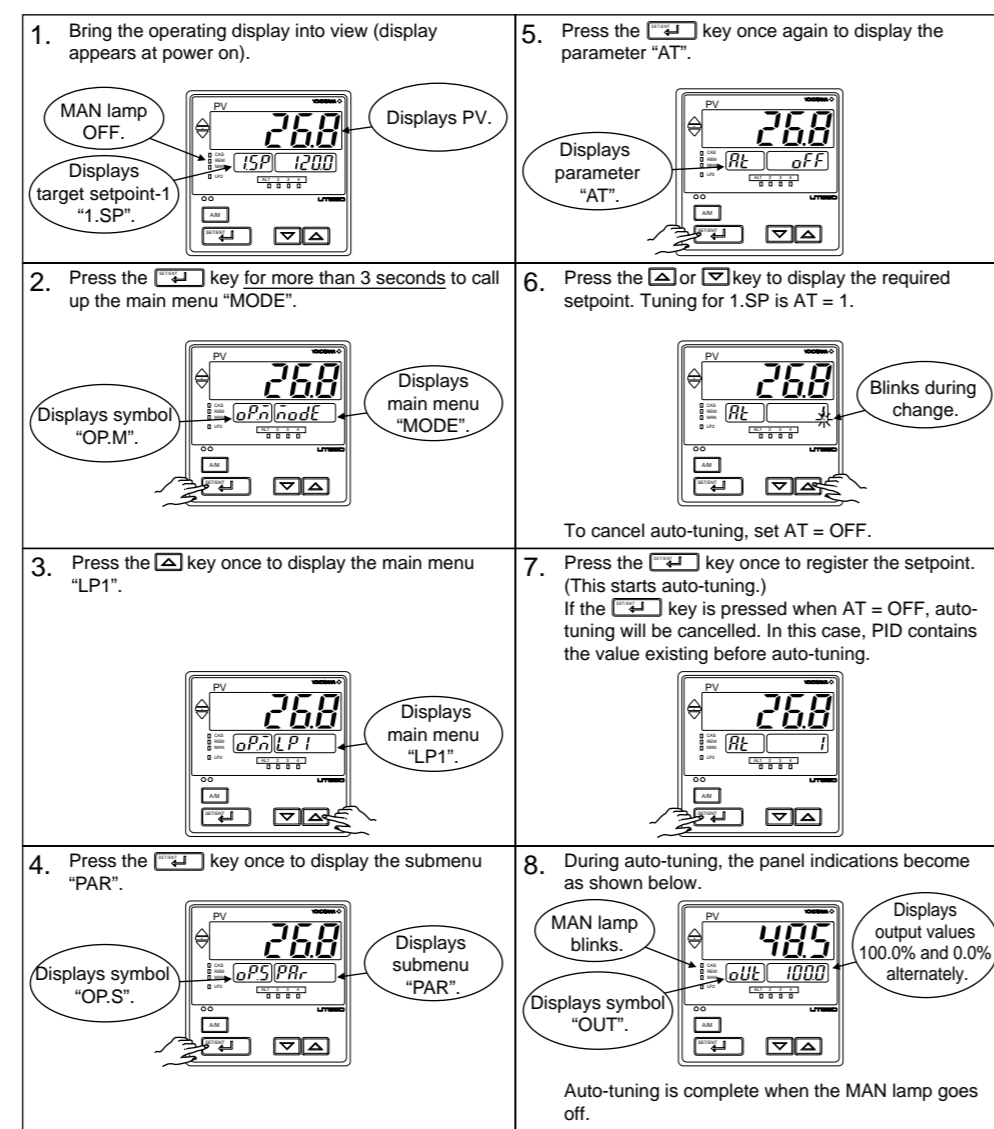


3. Performing/Canceling Auto-tuning

Auto-tuning should be carried out after setting a target setpoint (SP). Make sure the controller is in automatic operation mode (AUTO) and in running state (RUN) before carrying out auto-tuning. See "8. Switching between AUTO and MAN," to change to AUTO and "7. Switching between Run and Stop," to change to Run.

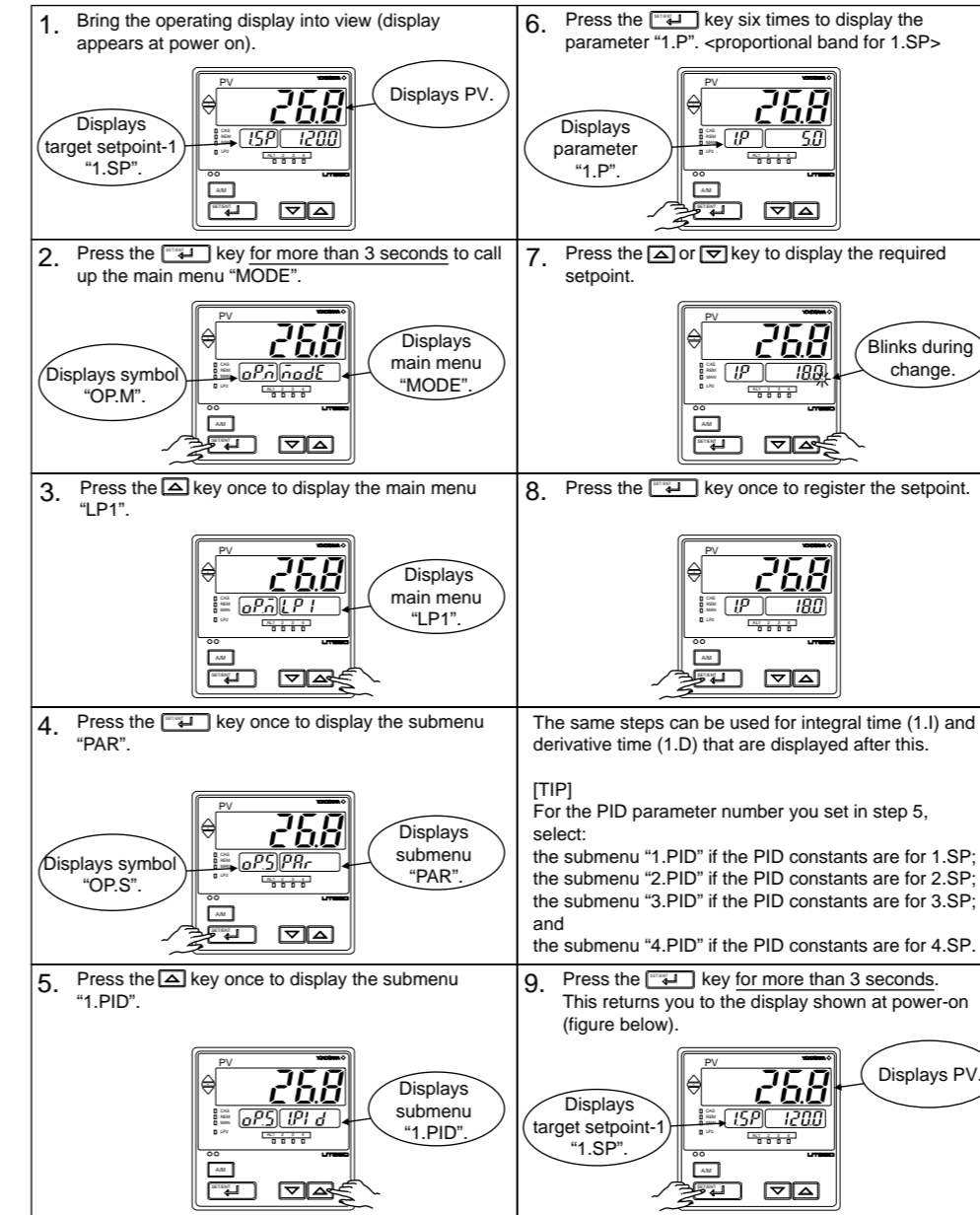
NOTE
 When on-off control is being used, auto-tuning cannot be carried out. Moreover, do not perform auto-tuning when controlling any of the following processes.

- Control processes with quick response such as flow control or pressure control
- Processes where even temporary output on/off results in inconvenience
- Processes where a large output change at control element results in inconvenience
- Processes where variations in PV may exceed an allowable range, adversely affecting product quality



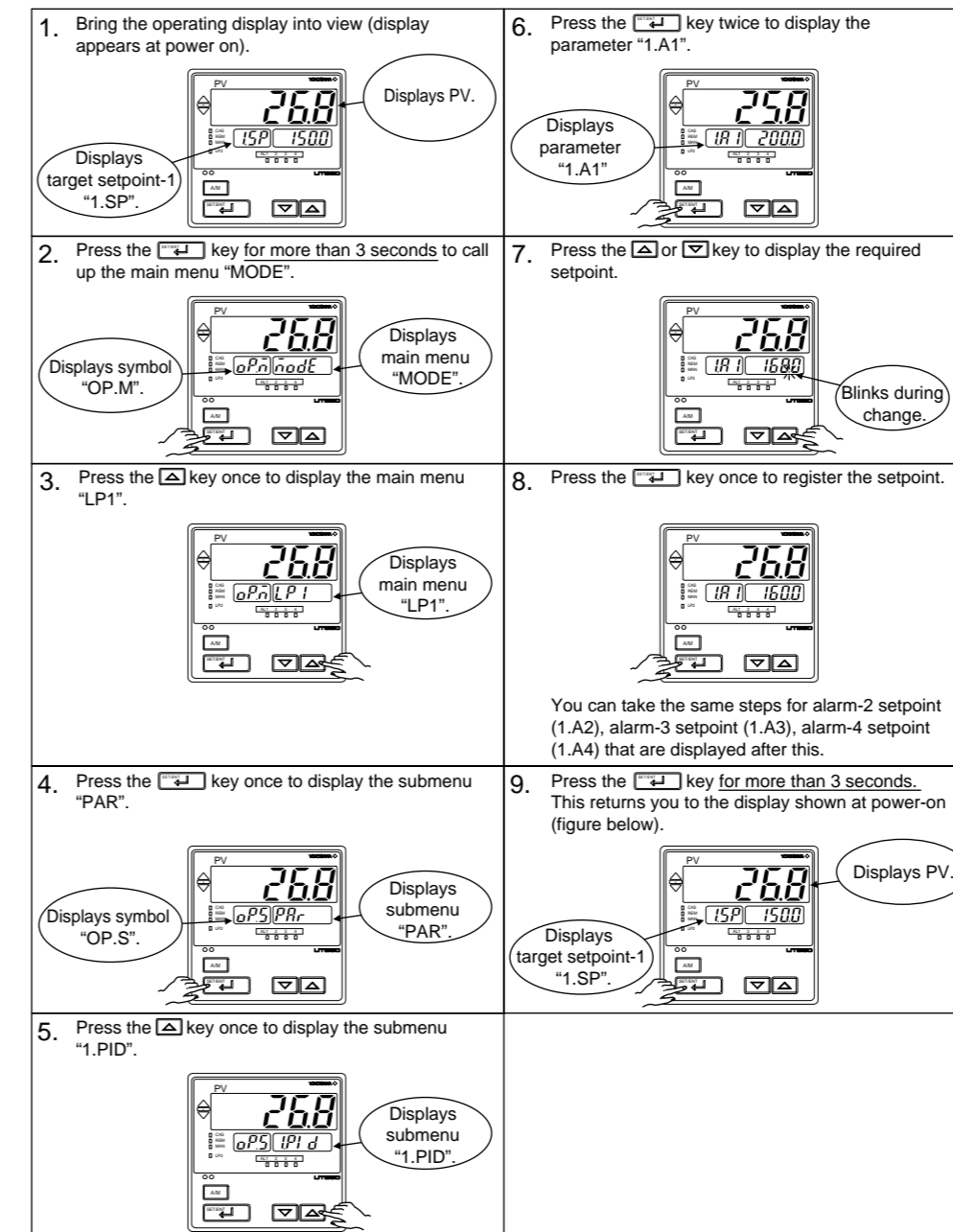
4. Setting PID Manually

If you know the values to be set or if suitable PID constants cannot be obtained by auto-tuning, follow the procedure below to set values.



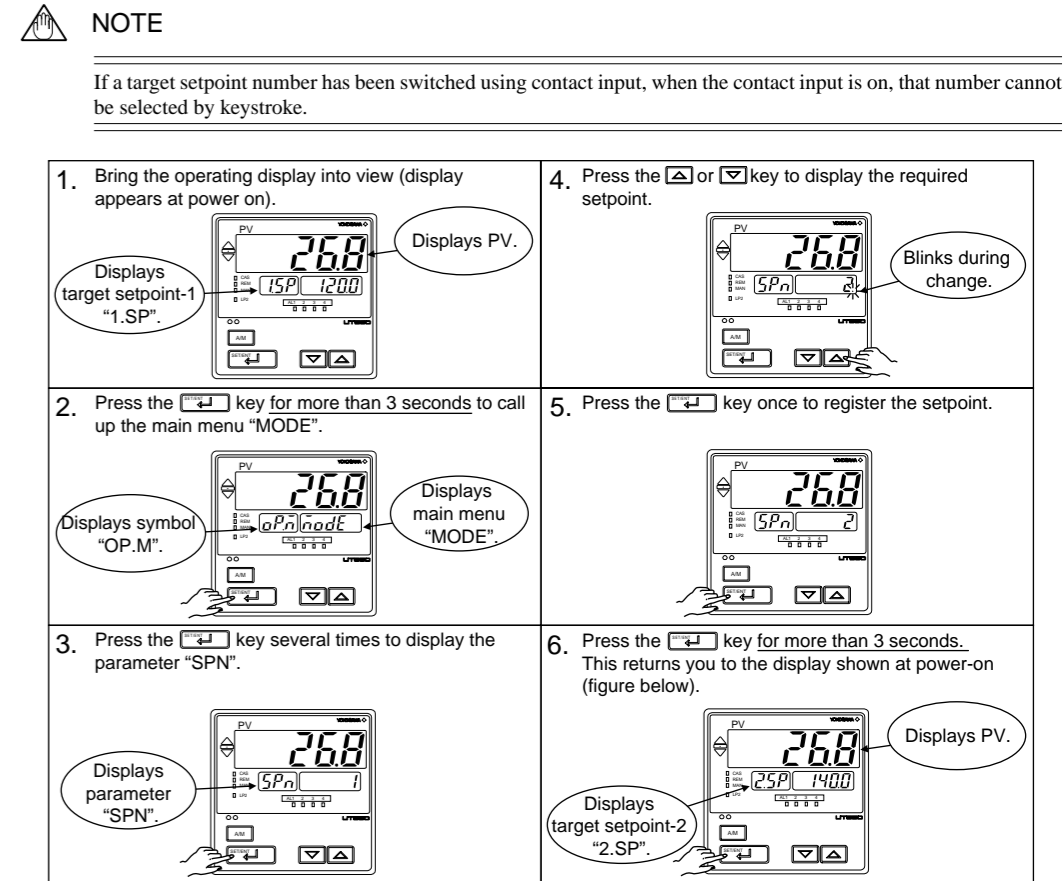
5. Setting Alarm Setpoints

The following operating procedure describes an example of setting 160.0 to alarm-1 setpoint. Check alarm type before setting the alarm setpoint. When changing the alarm type, see "7. Changing Alarm Type," in **Initial Settings User's Manual**.



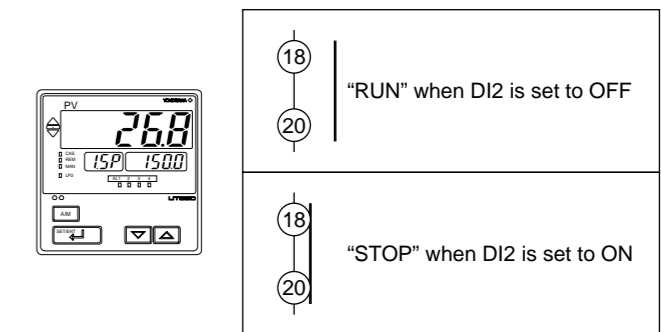
6. Selecting Target Setpoint Numbers (SPN)

The following operating procedure describes an example of changing a target setpoint number (SPN) from 1 to 2.



7. Switching between Run and Stop

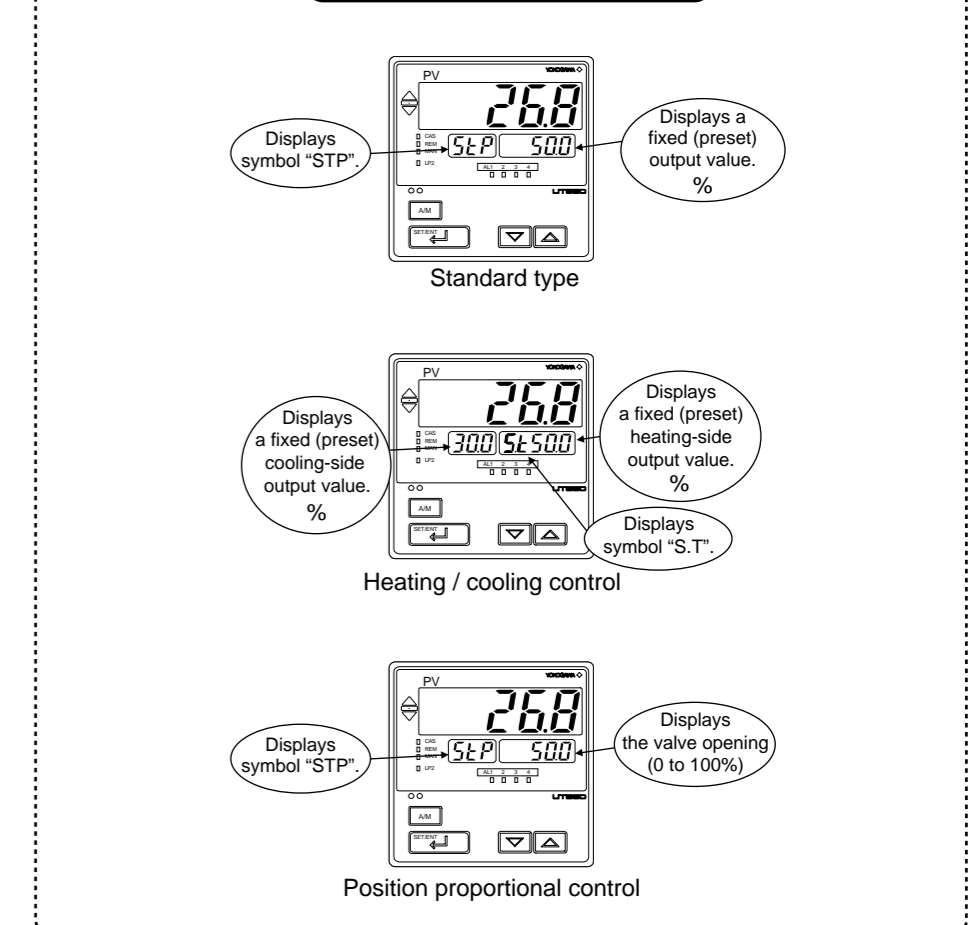
Switching between the Run state (RUN) and Stop state (STOP) can be made with contact input 2 (DI2). (Factory-set default)



When the controller is stopped, input and outputs are as follows:

PV input	Displays the PV value.
Control output	Provides the preset output value (factory-set to 0%).
Alarm output	Turns the output on in case of an alarm.

Output Display in STOP



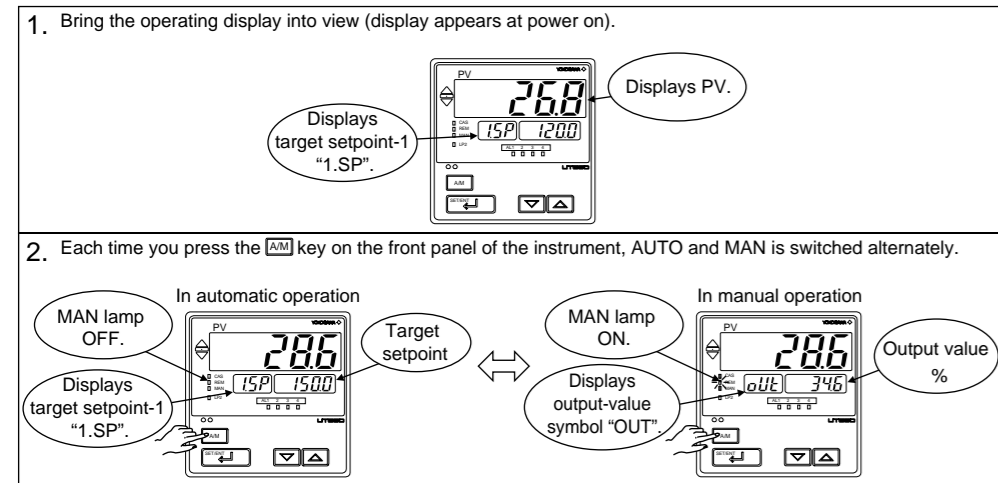
* Switching the target setpoint number (SPN) in STOP allows any preset output value (n.PO) to be switched. The "n" is same as the target setpoint number. In heating/cooling control, heating-side preset output value (n.PO) and cooling-side preset output value (n.Oc) are output.

8. Switching between AUTO and MAN



NOTE

If AUTO and MAN have been switched using contact input, when the contact input is ON, switching between AUTO and MAN cannot be achieved by keystroke.



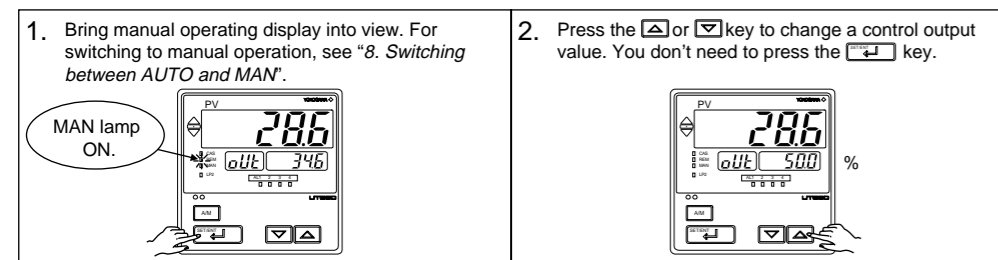
9. Manipulating Control Output during Manual Operation



NOTE

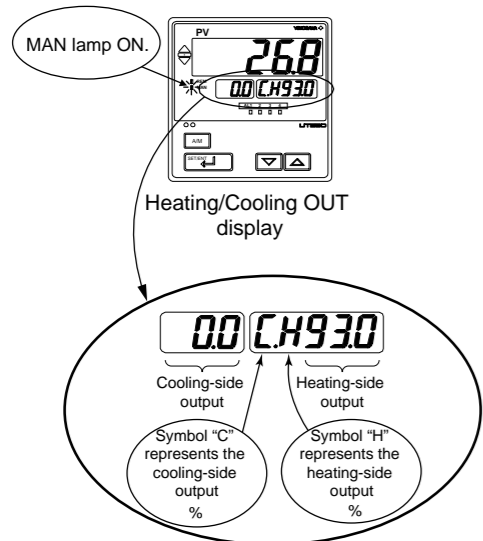
Control output cannot be changed if the controller is stopped. In this case, the preset output value (operating parameter PO) will be output. In heating / cooling control, the heating-side preset output value (operating parameter PO) and cooling-side preset output value (operating parameter Oc) will be output.

A control output value is linked with a display value changed using the key. Note that the control output changes as displayed without requiring the key.



Manipulating the Control Output during Heating/Cooling Control

Showing the Heating/Cooling OUT display.

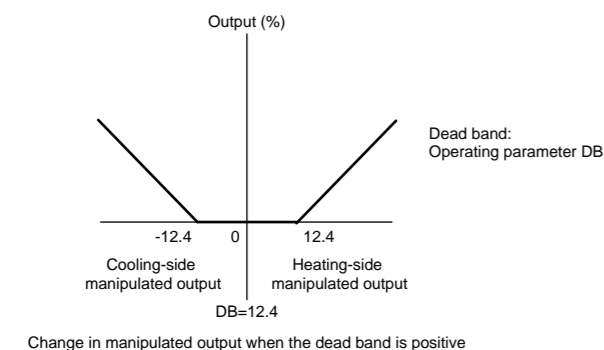


Controller behavior and control output manipulation when the dead band is positive

The following is an example when the DB parameter is set at 12.4%. If you hold down the key with the heating-side output under manipulation (i.e., cooling-side output C = 0.0%), the heating-side output (H =) decreases.

Consequently, both the heating-side and cooling-side outputs change to 0.0%. If you keep the key held down longer, you enter the state of manipulating the cooling-side output, and its value begins to increase.

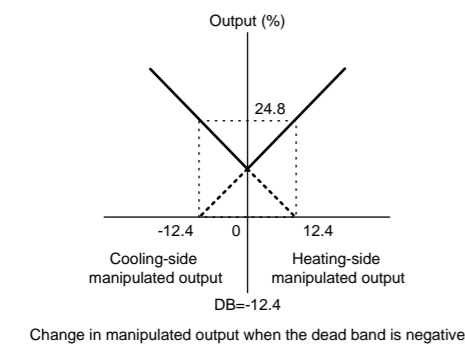
Inversely, if you hold down the key with the cooling-side output under manipulation (i.e., heating-side output H = 0.0%), the cooling-side output (C =) decreases. Consequently, both the heating-side and cooling-side outputs go to 0.0%. If you keep the key held down longer, you enter the state of manipulating the heating-side output, and its value begins to increase.



Controller behavior and control output manipulation when the dead band is negative

The following is an example when the DB parameter is set at -12.4%.

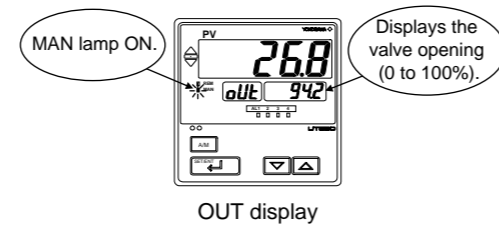
If you hold down the key with the heating-side output under manipulation (i.e., cooling-side output C = 0.0%), the heating-side output (H =) decreases. If the output H falls below 24.8%, the cooling-side output C begins to increase from 0.0%. If you keep the key held down longer and the output C rises above 24.8%, the output H goes to 0.0% and you enter the state of manipulating the cooling-side output.



Manipulating the Control Output during Position Proportional Control

The controller continues to provide control output as long as the key or key is being pressed.

- key: Closes the valve.
- key: Opens the valve.



Note: Manual output is not limited to output high limit(OH) and output low limit(OL).

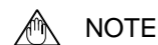
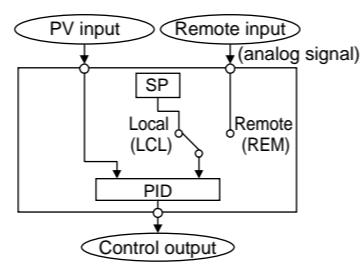
10. Switching between Remote (REM) and Local (LCL)

The following operating procedure describes an example of switching from Local (LCL) to Remote (REM).

Switching between REM and LCL is possible for only controllers with remote input.

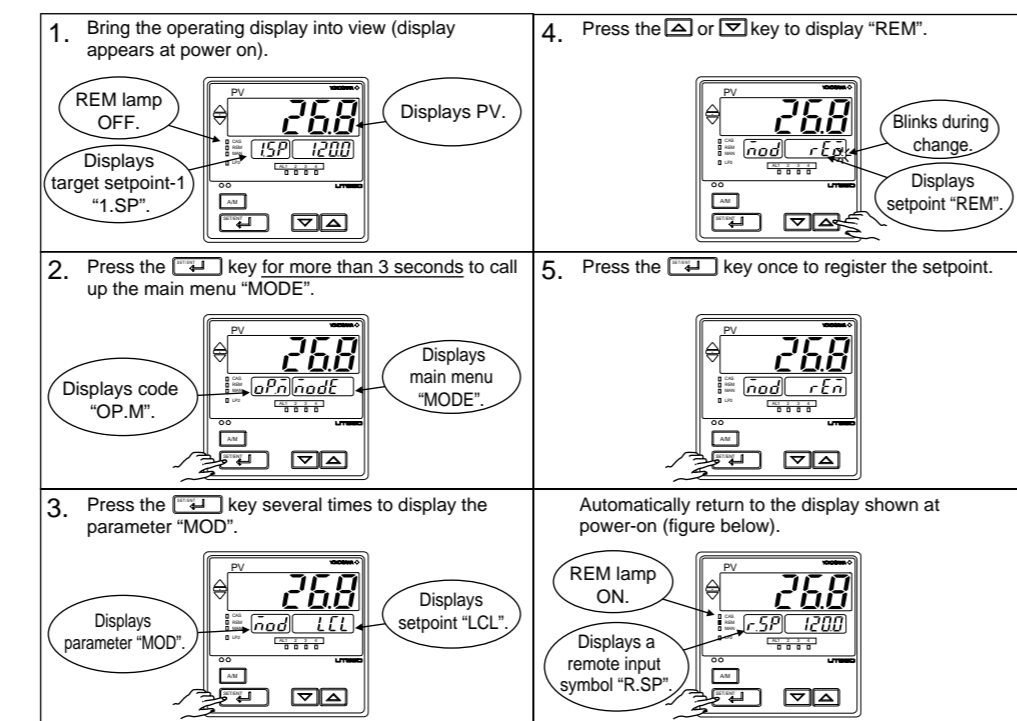
- Local: Performs control using target setpoints set in the controller.
- Remote: Performs control using external analog signals as target setpoints.

Note: The PID group number when the controller is in Remote operation is the same as the number set in the Target Setpoint Number (SPN) parameter.



NOTE

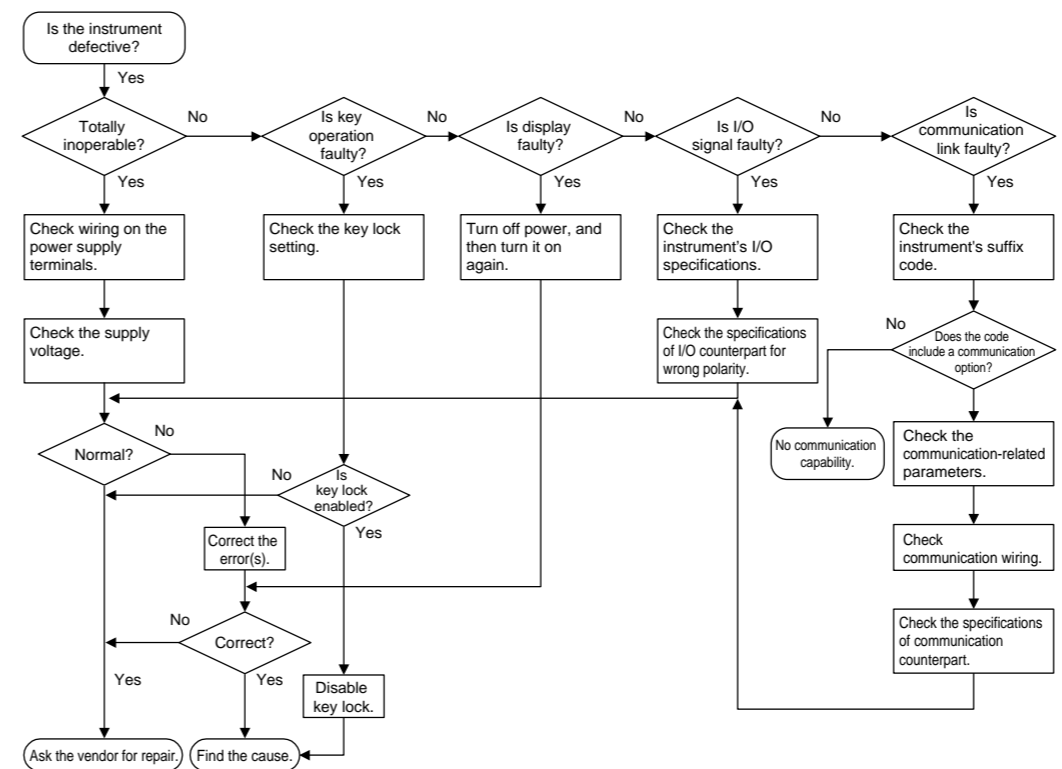
If Remote state is achieved by external contact input (contact input is ON), switching between REM and LCL cannot be achieved by keystroke.



11. Troubleshooting

Troubleshooting Flow

If the operating display does not appear after turning on the controller's power, follow the measures in the procedure below. If a problem appears complicated, contact our sales representative.



IMPORTANT

Take note of the parameter settings when asking the vendor for repair.

Errors at Power On

The following table shows errors that may be detected by the fault diagnosis function when the power is turned on.

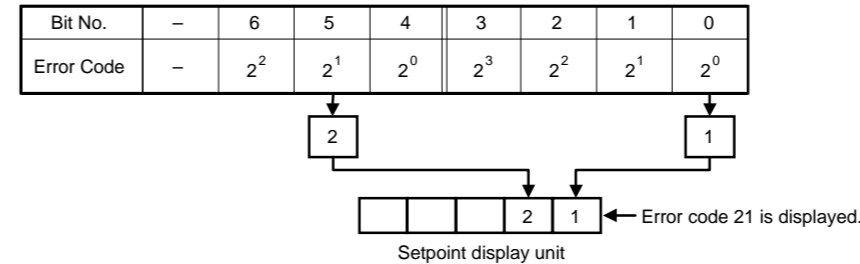
Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmission output	Communication	Remedy
E000 (E000)	Faulty RAM	None	0% or less or OFF	OFF	0% or less	Stopped	Faulty Contact us for repair.
E001 (E001)	Faulty ROM	None	0% or less or OFF	OFF	0% or less	Stopped	
E002 (E002)	System data error	Undefined	Normal action (out of accuracy)	Undefined	Undefined	Normal action (out of accuracy)	
PV decimal point blinks	Faulty calibration value	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Check and set the initialized parameters.
Error code (Note) (See description below.)	Parameter error	Normal action	0% or less or OFF	Normal action	Normal action	Normal action	

Note: An error code is displayed on the setpoint display unit.

An error code is displayed in the event of an error, according to its type. An error code is a two-digit figure in which a combination of 6 bits of on and off is converted into a decimal number. The following shows the relationship between each bit and parameter to be checked for abnormality.

Bit No.	6	5	4	3	2	1	0
Parameter to be checked	Operation mode/output	Operating parameters	Setup parameters	Range data	UT mode	-	Calibration data

For example, if an error occurs with the operating parameter and calibration data, the error code will be as follows:



Possible Errors during Operation

The following shows possible errors occurring during operations.

Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmission output	Communication	Remedy
Displays "RJC" and PV alternately	RJC error	Measured with RJC=OFF	Normal action				Faulty Contact us for repair.
Decimal point of item part in SP display unit blinks.	EEPROM error	Normal action					
E300 (E300)	ADC error	105%	In AUTO: Preset value output In MAN: Normal action				Check wires and sensor.
baUt (B.OUT)	PV burnout error	Dependent on the BSL parameter Up-scale: 105% Down-scale: -5%			Normal action		
oHEr (OVER) or -aBEr (-OVER)	Excessive PV Out of -5 to 105%	-5% or 105%	Normal action	Normal action		Normal action	Check process.
E200 (E200)	Auto-tuning failure (Time-out)		Action with PID existing before auto-tuning				Check process. Press any key to erase error indication.
Setpoint display	Feedback resistor breakdown	Normal action	Stopped		Stopped		Check the feedback resistor.
Left end of SP display unit blinks.	Faulty communication line		Normal action		Normal action		Check wires and communication parameters, and make resetting. Recovery at normal receipt
Decimal point at right end lights.	Runaway (due to defective power or noise)	Undefined	0% or less or OFF	OFF	0% or less	Stopped	Faulty if power off/on does not reset start the unit. Contact us for repair.
All indications off	Power off	None					Check for abnormal power.

Remedies if Power Failure Occurs during Operations

The operation status and remedies after a power failure differ with the length of power failure time:

- Instantaneous power failure of 20 ms or less: A power failure is not detected. Normal operation continues.
- Power failure of about 2 seconds or less: The following show effects caused in "settings" and "operation status."

Alarm action	Continues. Alarm with standby function will enter standby status.
Setting parameter	Set contents of each parameter are retained.
Auto-tuning	Cancelled.
Control action	Action before power failure continues.

- Power failure of more than about 2 seconds: The following show effects caused in "settings" and "operation status."

Alarm action	Continues. Alarm with standby function will enter standby status.
Setting parameter	Set contents of each parameter are retained.
Auto-tuning	Cancelled.
Control action	Differs with setting of setup parameter "R.MD" (restart mode). R.MD setting: Control action after recovery from power failure CONT: Continues action before power failure. (Factory-set default) For position-proportional type, when V.MD = Valve position estimating type, starts action from 0%. MAN: Outputs preset output value (PO) as control output and continues action set before power failure in MAN mode. For position-proportional type, when V.MD = Valve position feedback type, starts action from feedback input condition at recovery from power failure. When V.MD = Valve position estimating type, starts action from 0%. For heating/cooling control, starts action from heating-side output value and cooling-side output value of 50% of control computation output. AUTO: Outputs preset output value (PO) as control output and continues action set before power failure in AUTO mode. For position-proportional type, when V.MD = Valve position feedback type, starts action from feedback input condition at recovery from power failure. When V.MD = Valve position estimating type, starts action from 0%. For heating/cooling control, starts action from heating-side output value and cooling-side output value of 50% of control computation output.

Troubleshooting When the Controller Fails to Operate Correctly

If your control tasks are not successful, check the preset parameters and controller wiring before concluding the controller to be defective. The following show some examples of troubleshooting you should refer to in order to avoid the possibility of other problems.

The controller does not show the correct measured input (PV).

- The UT551 controller has a universal input. The type of PV input can be set/changed using the parameter "INI". At this point, the controller must be wired correctly according to the selected type of PV input. Check the wiring first if the controller fails to show the correct PV value. To do this, refer to **Initial Settings User's Manual**. With the parameters "RH1", "RL1", "DP1", "SH1" and "SL1", it is possible to scale the input signal and change its number of decimal places. Also check that these parameters are configured correctly.

The controller does not provide any control output or the control output does not change at all.

- The UT551 controller has a universal output. The type of control output can be set/changed using the parameter "OT1". At this point, the controller must be wired correctly according to the selected type of control output. Check the wiring first if the controller provides no control output. To do this, refer to "6. Terminal Wiring Diagrams," in **Installation User's Manual**. With the parameters "OH" and "OL", it is possible to set/change the high and low limits of control output. The control output may not change at all, however, because of restrictions on these parameters. Also check the restrictions on these parameters.

- The control output can only be changed when the controller is in the MAN mode. If the MAN lamp is off (i.e., the controller is in the AUTO mode), you cannot change the control output using key operation.

The control output does not change soon after the target setpoint (SP) has been changed.

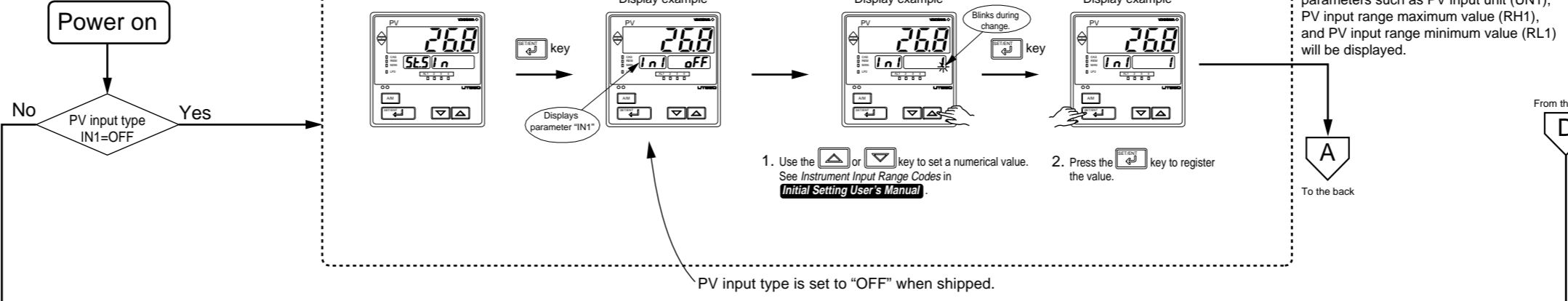
- If this happens, check the setpoint of the parameter "MOD". In cases where fixed-point control is selected as the PID control mode (MOD = 1), tracking based on the I-term works to prevent the control output from changing suddenly even if the target setpoint SP is varied. The control output therefore may appear to be working incorrectly at first; however it gradually adapts itself to the new target setpoint.



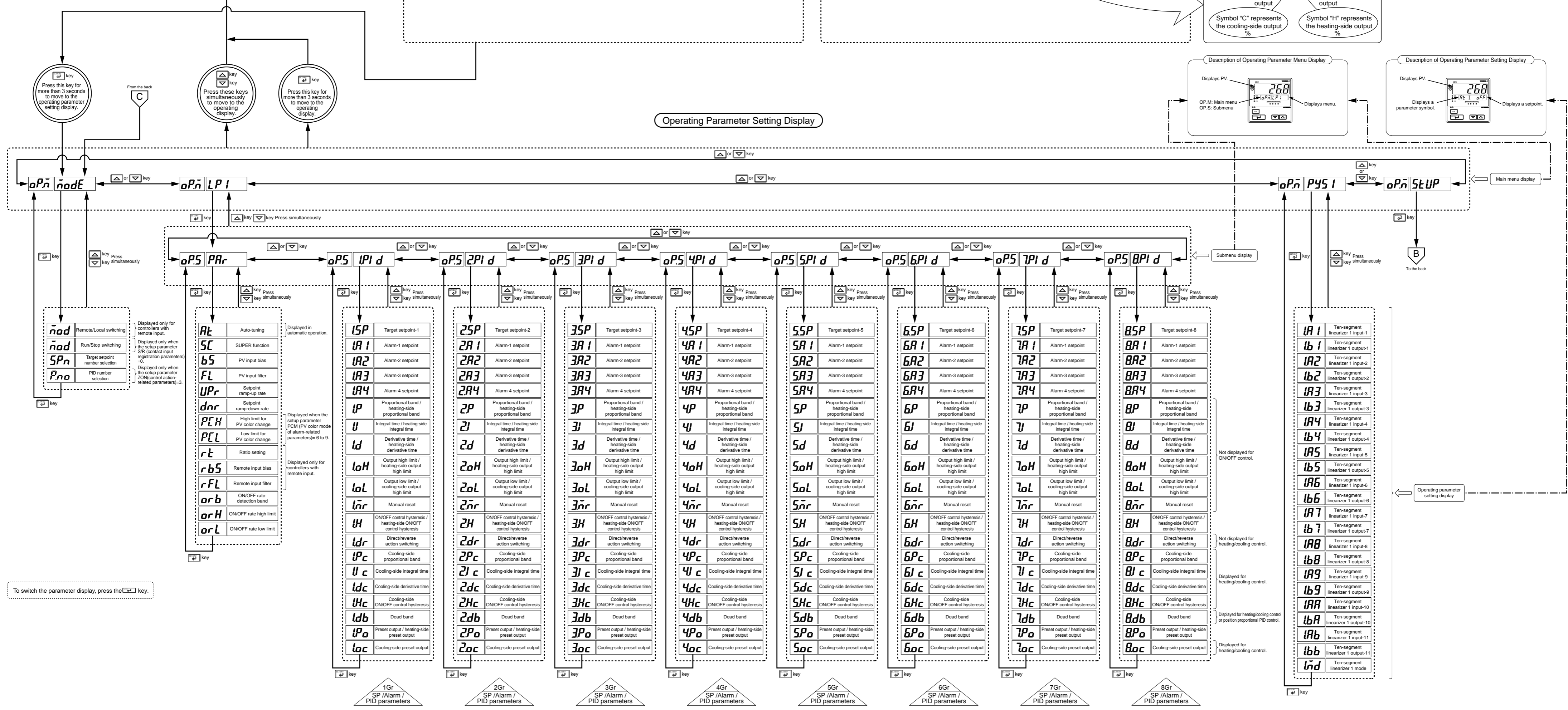
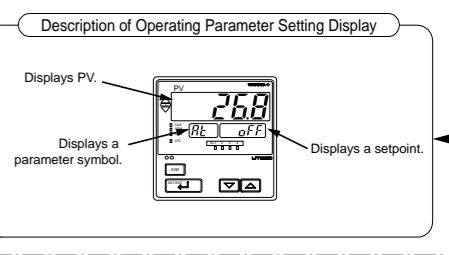
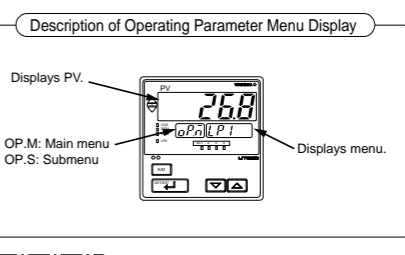
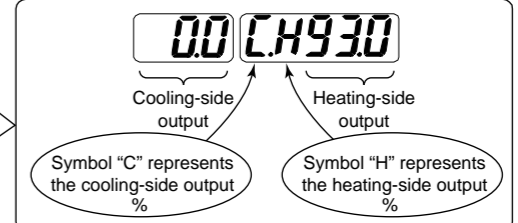
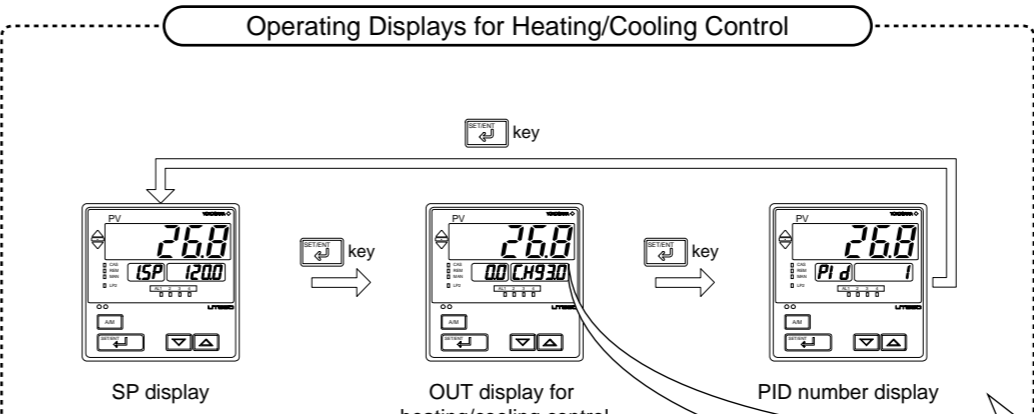
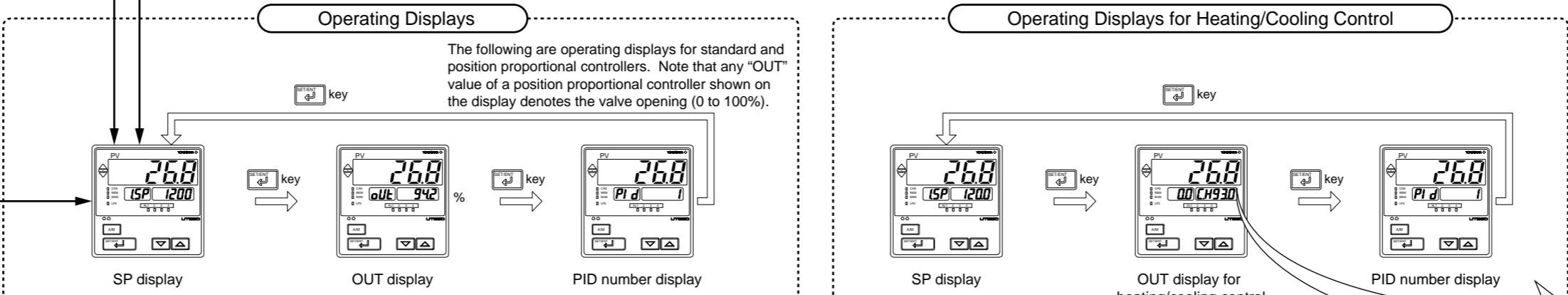
This manual contains a parameter map as a guideline for setting parameters.

If you are unsure of the key operation sequence, press the **key** (for more than 3 seconds). This displays a screen at power on (i.e., operating display).

Determine PV input type first. Settings herein are described in "2. Setting PV Input Type (Setting First at Power-on)", in **Initial Settings User's Manual**.

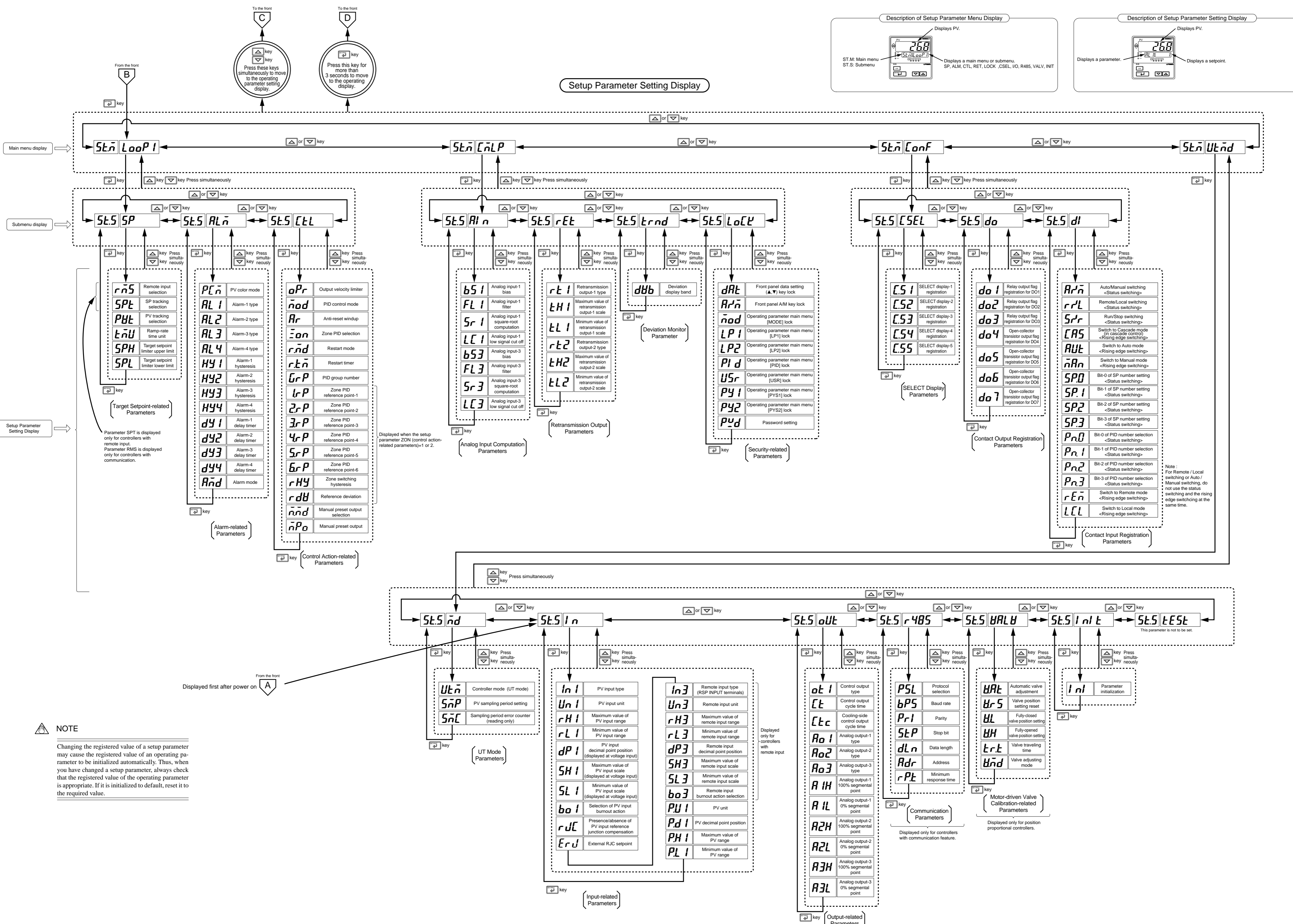
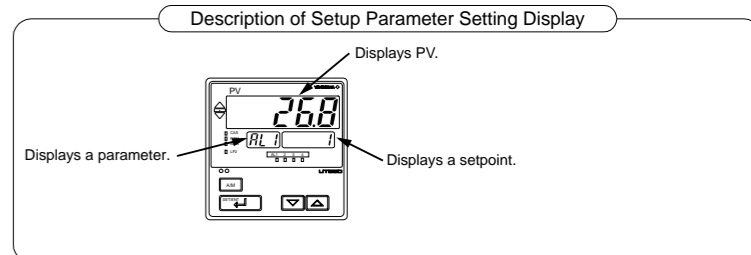
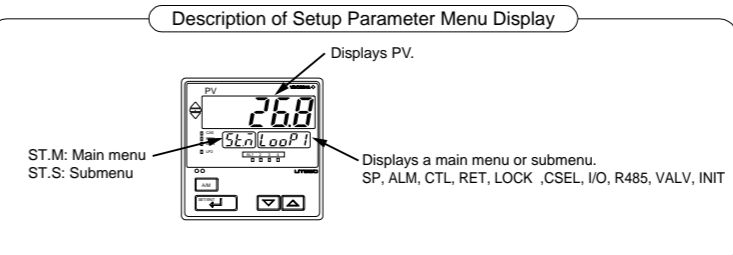


- Basic Key Operation Sequence**
- Setting display can be switched (moved) using the **key**.
 - A numerical value is changed by (1) Using the **key** or **key** to change a displayed value (decimal point blinking) and (2) Pressing the **key** to register it.
 - Pressing the **key** on an operating display (for more than 3 seconds) brings you to the operating parameter setting display.
 - Pressing the **key** on the operating parameter setting display (for more than 3 seconds) returns you to the operating display. To change from the operating parameter setting display to the operating parameter menu display, press the **key** and **key** simultaneously.
 - Pressing the **key** on the setup parameter setting display (for more than 3 seconds) returns you to the setup display. To change from the setup parameter setting display to the setup parameter menu display, press the **key** and **key** simultaneously.



To switch the parameter display, press the **key**.

Setup Parameter Setting Display



Parameter SPT is displayed only for controllers with remote input. Parameter RMS is displayed only for controllers with communication.

Note:
For Remote / Local switching or Auto / Manual switching, do not use the status switching and the rising edge switching at the same time.

NOTE
Changing the registered value of a setup parameter may cause the registered value of an operating parameter to be initialized automatically. Thus, when you have changed a setup parameter, always check that the registered value of the operating parameter is appropriate. If it is initialized to default, reset it to the required value.



IM 05D01C04-05E

Parameters

1st Edition: Mar. 25, 2005



This manual describes the functions of parameters briefly. In addition, each parameter table has a "User Setting" column, where you can record your setpoints when setting them in the controller.

* Parameters relating to PV or setpoints should all be set in real numbers. For example, use temperature values to define target setpoints and alarm setpoints for temperature input.

Operating Parameters

Operation Mode Parameters

Located in: Main menu = **MODE** (MODE)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
nod (MOD)	Remote/Local switching	Set to "Local" when carrying out control using the target setpoints of the controller or to "Remote" when using target setpoints acquired via a remote input signal or communication. Use the setup parameter RMS, "Remote Input Selection," to determine whether the target setpoints should be acquired via the remote input signal or communication. REM: Remote mode LCL: Local mode	LCL		—
nod (MOD)	Run/Stop switching	Outputs the predetermined (preset) fixed value when the controller stops. A preset output value can be defined for each target setpoint using the operating parameter "PO". Stop: Stops operation. Run: Starts operation.	RUN		—
SPn (SPN)	Target setpoint number selection	1: Selects target setpoint-1 (1.SP); 2: Selects target setpoint-2 (2.SP); 3: Selects target setpoint-3 (3.SP); 4: Selects target setpoint-4 (4.SP). Likewise, options 5 to 8 select target setpoints 5 (5.SP) to 8 (8.SP).	1		—
Pno (P.NO)	PID number selection	Displayed when the setup parameter "ZON"=3. Setting range: Depends on the setup parameter "GRP". This parameter cannot be set when the PID number is selected by DI. Displays PID number only.	1		—

Operation-related Parameters

Located in: Main menu = **LP1** (LP1); Submenu = **PARr** (PAR)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
AT (AT)	Auto-tuning	OFF: No auto-tuning 1: Auto-tuning for 1.SP 2: Auto-tuning for 2.SP 3: Auto-tuning for 3.SP 4: Auto-tuning for 4.SP 5 to 8: Perform auto-tuning on a group basis in the same way as 1 to 4 9: Performs auto-tuning to all groups 1 to 8.	OFF		—
SC (SC)	"SUPER" function	OFF: Disable 1: Suppresses overshoots generated by abrupt changes in the target setpoint or by disturbances. 2: Hunting suppressing function (Stable mode) Suitable to stabilize the state of control when the load varies greatly, or the target setpoint is changed. Enables to answer the wider characteristic changes compared with Response mode. 3: Hunting suppressing function (Response mode) Enables quick follow-up and short converging time of PV for the changed target setpoint. Note: Use "SUPER" function (SC) 2 or 3 in PID control or PI control. "SUPER" function 2 or 3 is not available in the following controls: 1) ON/OFF control 2) P control (control for proportional band only) 3) PD control (control for proportional band and derivative item only) 4) Heating/cooling control Do not use hunting suppressing function when control processes with response such as flow or pressure control.	OFF		Ref.2.1(5) Ref.2.1(6)
BS (BS)	PV input bias	-100.0% to 100.0% of PV input range span Used to correct the PV input value.	0.0% of PV input range span		Ref.1.1(1)
FL (FL)	PV input filter	OFF, 1 to 120 second Used when the PV input value fluctuates.	OFF		Same as above
UPr (UPR)	Setpoint ramp-up-rate	OFF 0.0% + 1 digit of PV input range span to 100.0% of PV input range span Set ramp-up-rate or ramp-down-rate per hour or minute. Sets unit in ramp-rate-time unit (TMU).	OFF		Ref.4.1(4)
dnr (DNR)	Setpoint ramp-down-rate	Used to prevent the target setpoint from changing suddenly. The ramp setting function works when: 1. the target setpoint is changed (e.g., "1.SP" is changed from 100°C to 150°C). 2. the target setpoint number (SPN) is changed (e.g., the parameter is changed from 1.SP to 2.SP). 3. the power is turned on or has recovered from a failure; or 4. the operating mode is changed from Manual to Auto.	OFF		Same as above
PCH (PCH)	High limit for PV color change	When PCM (PV color mode parameter) = 6 or 7: -100.0 to 100.0 % of PV input range When PCM = 6 or 7: PCH = 100.0%, PCL = 0.0 %	—		—
PCL (PCL)	Low limit for PV color change	When PCM (PV color mode parameter) = 8 or 9: -100.0 to 100.0 % of PV input range span When PCM = 8 or 9: PCH and PCL = 1.0 %	—		—
rt (RT)	Ratio setting	0.001 to 9.999 Target setpoint = Remote input × Ratio setpoint + Remote bias	1.000		Ref.1.2(3)
rb5 (RBS)	Remote input bias	-100.0 to 100.0% of PV input range span Used to correct the remote input value.	0.0% of PV input range span		Same as above
rFL (RFL)	Remote input filter	OFF, 1 to 120 second Used when the remote input value fluctuates.	OFF		Same as above
orb (ORB)	ON/OFF rate detection band	0.0 to 100.0% of PV input range span	1.0% of PV input range span		Ref.3.3(4)
orH (ORH)	ON/OFF rate high limit	ORL + 1 digit to 105.0%	100.0 %		Same as above
orL (ORL)	ON/OFF rate low limit	-5.0% to ORH - 1 digit	0.0%		Same as above

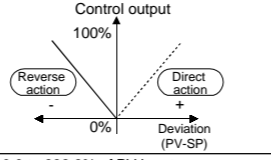
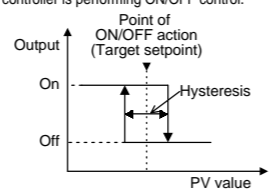
* The "User Setting" column in the table below is provided for the customer to record setpoints.
 * The column "Target Item in CD-ROM" in the table below provides references from User's Manual (Reference) (CD-ROM Version) which describes items in more detail and items that are not contained in this manual.

Setpoint-, Alarm- and PID-related Parameters

Located in: Main menu = **LP1** (LP1); Submenu = **IP1d** (1.PID)

The table below lists the Target Setpoint-1 (1.SP) operating parameter and parameters that apply to the 1.SP parameter.

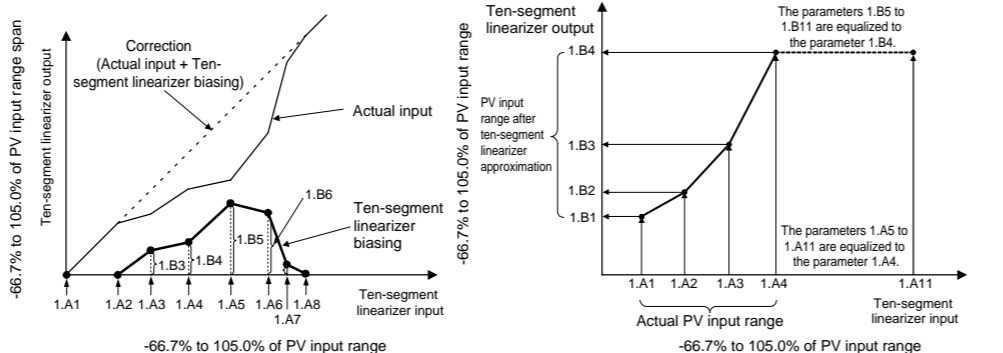
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
1SP (1.SP)	Target setpoint-1	0.0 to 100.0% of PV input range However, between target setpoint limiter lower limit (SPL) and upper limit (SPH)	0.0% of PV input range		Ref.4.1(1)
1A1 (1.A1)	Alarm-1 setpoint	PV alarm / SP alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Output alarm: -5.0 to 105.0% Timer alarm (for alarm-1 only): 0.00 to 99.99 (hour, min) or (min, sec)	PV high limit/SP high limit alarm: 100.0% of PV input range Deviation alarm: 0.0% of PV input range span Other PV/SP low limit alarm: 0.0% of PV input range Output high limit alarm: 100.0% Output Low limit alarm: 0.0%		Same as above
1A2 (1.A2)	Alarm-2 setpoint	Same as 1A1	Same as above		Same as above
1A3 (1.A3)	Alarm-3 setpoint	Same as 1A1	Same as above		Same as above
1A4 (1.A4)	Alarm-4 setpoint	Same as 1A1	Same as above		Same as above
1P (1.P)	Proportional band/Heating-side proportional band (in heating/cooling control)	0.1 to 999.9% of PV input range In heating/cooling control: 0.0 to 999.9% (heating-side on/off control applies when 0.0)	5.0%		Same as above
I (I)	Integral time Heating-side integral time (in heating/cooling control)	OFF, 1 to 6000 second	240 second		Same as above
Id (I.D)	Derivative time Heating-side derivative time (in heating/cooling control)	OFF, 1 to 6000 second	60 second		Same as above
1OH (1.OH)	Output high limit Heating-side output high limit (in heating/cooling control)	-5.0 to 105.0% Heating-side output high limit (in heating/cooling control): 100.0%	100% Heating/cooling control: 100.0%		Ref.2.1(3)
1OL (1.OL)	Output low limit Cooling-side output high limit (in heating/cooling control)	-5.0 to 105.0% Cooling-side limiter in heating/cooling control: 0.0 to 105.0% (1.OL < 1.OH) SD (shutdown): Set in manual operation in 4.20 mA control output.	0.0% Heating/cooling control: 100.0%		Ref.4.1(1)
1nr (1.MR)	Manual reset	-5.0 to 105.0% (enabled when integral time "I.I" is OFF) The manual reset value is 50%, the output value is 50% when PV = SP. For example, true.	50.0%		Ref.4.1(1)
1H (1.H)	ON/OFF control hysteresis Heating-side ON/OFF control hysteresis (in heating/cooling control)	In ON/OFF control: 0.0 to 100.0% of PV input range span Position proportional PID control or heating/cooling control: 0.0 to 100.0% Hysteresis can be set in the target setpoint when the controller is performing ON/OFF control.	ON/OFF control: 0.5% of PV input range span Position proportional PID control and heating/cooling control: 0.5%		Same as above



Ten-segment Linearizer1 Parameters

Located in: Main menu = **PYS1** (PYS1)

Ten-segment linearizer biasing (factory-set default) Ten-segment linearizer approximation



Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
1A1 (1.A1)	Ten-segment linearizer 1 input-1	-66.7% to 105.0% of PV input range	0.0% of PV input range		Ref.1.1(2)
1B1 (1.B1)	Ten-segment linearizer 1 output-1	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A2 (1.A2)	Ten-segment linearizer 1 input-2	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B2 (1.B2)	Ten-segment linearizer 1 output-2	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above

1A3 (1.A3)	Ten-segment linearizer 1 input-3	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B3 (1.B3)	Ten-segment linearizer 1 output-3	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A4 (1.A4)	Ten-segment linearizer 1 input-4	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B4 (1.B4)	Ten-segment linearizer 1 output-4	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A5 (1.A5)	Ten-segment linearizer 1 input-5	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B5 (1.B5)	Ten-segment linearizer 1 output-5	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A6 (1.A6)	Ten-segment linearizer 1 input-6	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B6 (1.B6)	Ten-segment linearizer 1 output-6	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A7 (1.A7)	Ten-segment linearizer 1 input-7	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B7 (1.B7)	Ten-segment linearizer 1 output-7	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A8 (1.A8)	Ten-segment linearizer 1 input-8	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B8 (1.B8)	Ten-segment linearizer 1 output-8	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A9 (1.A9)	Ten-segment linearizer 1 input-9	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B9 (1.B9)	Ten-segment linearizer 1 output-9	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A10 (1.AA)	Ten-segment linearizer 1 input-10	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B10 (1.BA)	Ten-segment linearizer 1 output-10	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1A11 (1.AB)	Ten-segment linearizer 1 input-11	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
1B11 (1.BB)	Ten-segment linearizer 1 output-11	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
1nd (1.MD)	Ten-segment linearizer 1 mode	0: Ten-segment linearizer biasing 1: Ten-segment linearizer approximation	0		Same as above

Setup Parameters

Target Setpoint-related Parameters

Located in: Main menu = **LOOP1** (LOOP1); Submenu = **SP** (SP)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
rns (RNS)	Remote input selection	RSP: Uses the value set remotely via remote input (terminals). COM: Uses the value set remotely via communication.	RSP		Ref.1.2(1)
SPT (SPT)	SP tracking selection	OFF, ON Tracking is performed when the mode changes from Remote to Local (The local setpoint keeps track of the remote setpoint.)	ON		Ref.1.2(4)
PST (PST)	PV tracking selection	Causes the setpoint to keep track of the PV value so the setpoint automatically reverts to its original value at a preset rate of change. The Setpoint Ramp-up rate (UPR) and Setpoint Ramp-down rate (DNR) parameters are used in combination. - Operating conditions - 1: Manual operation → Automatic operation; 2: Stop → Start of automatic operation; 3: Power on; 4: Change SP number; 5: Change SP value OFF: Disable ON: Enable	OFF		Ref.1.1(7)
TMU (TMU)	Ramp-rate time unit setting	Time unit of setpoint ramp-up rate (UPR) and setpoint ramp-down rate (DNR) HOUR: Denotes "per hour." MIN: Denotes "per minute."	HOUR		Ref.4.1(4)
SPH (SPH)	Target setpoint limiter upper limit	0.0% to 100.0% of PV input range. Note that SPL < SPH Places limits on the ranges within which the target setpoints (1.SP to 8.SP) are changed.	100.0% of PV input range		—
SPL (SPL)	Target setpoint limiter lower limit	0.0% to 100.0% of PV input range	0.0% of PV input range		—

Alarm-related Parameters

Located in: Main menu = **ALM1** (ALM1); Submenu = **ALN** (ALM)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
PCm (PCM)	PV color mode	0 to 9 0: Fixed in green 1: Fixed in red 2: Link to alarm 1 (Alarm OFF:green, Alarm ON:red) 3: Link to alarm 1 (Alarm OFF:red, Alarm ON:green) 4: Link to alarm 1 and 2 (Alarm OFF:green, Alarm ON:red) 5: Link to alarm 1 and 2 (Alarm ON:red, Alarm OFF:green) 6: PV limit (Within PV range:green, Out of PV range:red) 7: PV limit (Within PV range:red, Out of PV range:green) 8: SP deviation (Within deviation:green, Out of deviation:red) 9: SP deviation (Within deviation:red, Out of deviation:green)	1		—
AL1 (AL1)	Alarm-1 type	OFF, 1 to 31, 33 to 38, 43 to 48 (Same as below) Common to all target setpoints.	1		Ref.3.3(3) Ref.3.3(4)
AL2 (AL2)	Alarm-2 type	OFF, 1 to 20, 25 to 31, 33 to 38, 43 to 48 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action)	2		Ref.3.3(4)
AL3 (AL3)	Alarm-3 type	3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action)	1		Same as above
AL4 (AL4)	Alarm-4 type	For other alarm types, see "List of Alarm Types" in Initial Settings User's Manual. Common to all target setpoints.	2		Same as above
HY1 (HY1)	Alarm-1 hysteresis	0.0 to 100.0% of PV input range span Output alarm: 0.0 to 100.0%	0.5% of PV input range span Output alarm: 0.5%		Ref.3.3(2)
HY2 (HY2)	Alarm-2 hysteresis	Allows margins to be set for an alarm setpoint. With the hysteresis settings, it is possible to prevent relays from chattering.	Same as above		Same as above
HY3 (HY3)	Alarm-3 hysteresis	Hysteresis for PV high limit alarm	Same as above		Same as above
HY4 (HY4)	Alarm-4 hysteresis	Hysteresis for PV high limit alarm	Same as above		Same as above

dy1 (DY1)	Alarm-1 delay timer	0.00 to 99.99 (min. sec.) (enabled when alarm-1 type "AL1" is 1 to 20 or 28 to 31) An alarm is output when the delay timer expires after the alarm setpoint is reached.	0.00		—
dy2 (DY2)	Alarm-2 delay timer	0.00 to 99.99 (min. sec.) (enabled when alarm-2 type "AL2" is 1 to 20 or 28 to 31)	—		—
dy3 (DY3)	Alarm-3 delay timer	0.00 to 99.99 (min. sec.) (enabled when alarm-2 type "AL3" is 1 to 20 or 28 to 31)	—		—
dy4 (DY4)	Alarm-4 delay timer	0.00 to 99.99 (min. sec.) (enabled when alarm-4 type "AL4" is 1 to 20 or 28 to 31)	—		—
Rnd (AMD)	Alarm mode	Allows the alarm function to be enabled or disabled according to the operating condition. 0: Always active 1: Not active when in Stop mode 2: Not active when in Stop mode or manual operation 3: Eight alarms are used and always enabled. 4: Eight alarms are used and disabled when the controller is at a stop. 5: Eight alarms are used and disabled when the controller is at a stop or in manual operation.	0		Ref.3.3(1)

Control Action-related Parameters

Located in: Main menu = **LOOP1** (LOOP1); Submenu = **CTL** (CTL)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
OPr (OPR)	Output velocity limiter	OFF (0) 0.1 to 100.0%/second can limit control output velocity	OFF		—
MOD (MOD)	PID control mode	0: Standard PID control (with output bump at SP change) 1: Fixed-point control (without output bump at SP change) Choose "Fixed-point Control" when controlling pressure or flow rate.	0		Ref.2.1(2)
AR (AR)	Anti-reset windup (Excess integration prevention)	AUTO (0), 50.0 to 200.0% The larger setting, the sooner PID computation (integral computation) stops. Used when the control output travels up to 100% or down to 0% and stays at this point.	AUTO		Ref.2.1(4)
ZON (ZON)	Zone PID selection	0: selection 1: Zone PID (selecting by PV) 2: Zone PID (selects by target setpoint) 3: Selects by specified PID number. (operating parameter P.NO) If set to "SP selection," allows PID constants to be selected for each target setpoint. If set to "Zone PID," automatically selects PID constants according to the temperature range set in the given Reference Point parameter.	0		Ref.4.1(2)
rnd (R.MD)	Restart mode	CONT: Continues action set before power failure. MAN: Starts from manual operation status. AUTO: Continues action set before power failure in automatic operation. Allows you to determine how the controller should recover from a power failure of longer than 2 second	CONT		—
rtm (R.TM)	Restart timer	0 to 10 second Sets time between power on and the instant where controller starts computation.	0 second		—
GRP (GRP)	PID group number	Allows you to determine how many groups of setpoint, alarm and PID parameters the controller should show. 1: Show one set. 2: Show two sets. 3: Show three sets. 4: Show four sets. 5 to 8: Show as many groups of parameters as have been set.	8		Ref.4.1(1)
1RP (1.RP)	Zone PID reference point-1	0.0 to 100.0% of PV input range. Note that 1.RP ≤ 2.RP ≤ 3.RP ≤ 4.RP ≤ 5.RP ≤ 6.RP. Sets reference points at which switching is carried out between groups of PID constants according to the given temperature zone. You can set a maximum of six reference points and therefore a maximum of seven temperature zones. To enable this parameter, set the Zone PID Selection (ZON) parameter to "1" or "2".	100.0% of PV input range		Ref.4.1(2)
2RP (2.RP)	Zone PID reference point-2	Same as above	Same as above		Same as above
3RP (3.RP)	Zone PID reference point-3	Same as above	Same as above		Same as above
4RP (4.RP)	Zone PID reference point-4	Same as above	Same as above		Same as above
5RP (5.R					

● Retransmission Output Parameters

Located in: Main menu = **CLNP** (CMLP) ; Submenu = **REt** (RET)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters like rrt1, th1, tl1, rrt2, th2, tl2.

● Deviation Monitor Parameters

Located in: Main menu = **CLNP** (CMLP) ; Submenu = **TRnd** (TRND)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameter ddb.

● Security-related Parameters

Located in: Main menu = **CLNP** (CMLP) ; Submenu = **LoLk** (LOCK)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters drl, arrn, nod, lpl1, lpl2, pld, usr, py1, py2, pwd.

● SELECT Display Parameters

Located in: Main menu = **CONF** (CONF) ; Submenu = **CSEL** (CSEL)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters cs1, cs2, cs3, cs4, cs5.

● Contact Output Registration Parameters

Located in: Main menu = **CONF** (CONF) ; Submenu = **DO** (DO)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters do1, do2.

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters do3, do4, do5, do6, do7.

● Contact Input Registration Parameters

Located in: Main menu = **CONF** (CONF) ; Submenu = **DI** (DI)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters arrn, rrl, sr, cas, aut, man, sp0, sp1, sp2, sp3, pn0, pn1, pn2, pn3, ren, lcl.

● UT Mode Parameters

Located in: Main menu = **UTMD** (UTMD) ; Submenu = **MD** (MD)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters utm, gmp, smc.

● Input-related Parameters

Located in: Main menu = **UTMD** (UTMD) ; Submenu = **IN** (IN)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters in1, un1, rh1, rl1, dp1, sh1, sl1, bo1, rjc, erj, in3, un3.

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters rh3, rl3, dp3, sh3, sl3, bo3, pu1, pd1, ph1, pl1.

● Output-related Parameters

Located in: Main menu = **UTMD** (UTMD) ; Submenu = **OUT** (OUT)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters ot1, ct, etc, ro1, ro2, ro3, ah, al, a2h, a2l, a3h, a3l.

■ Performing Split Computations

Text explaining V-mode output and split computations. Includes a graph showing output rate after computation vs output value before split computation.

● Communication Parameters

Located in: Main menu = **UTMD** (UTMD) ; Submenu = **r485** (R485)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters psl, bps, pri, stp, dl, adr, rpt.

● Motor-driven Value Calibration-related Parameters (Displayed for Position Proportional Controllers)

Located in: Main menu = **UTMD** (UTMD) ; Submenu = **VALV** (VALV)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameters val, brs, vl, vh, trt, vmd.

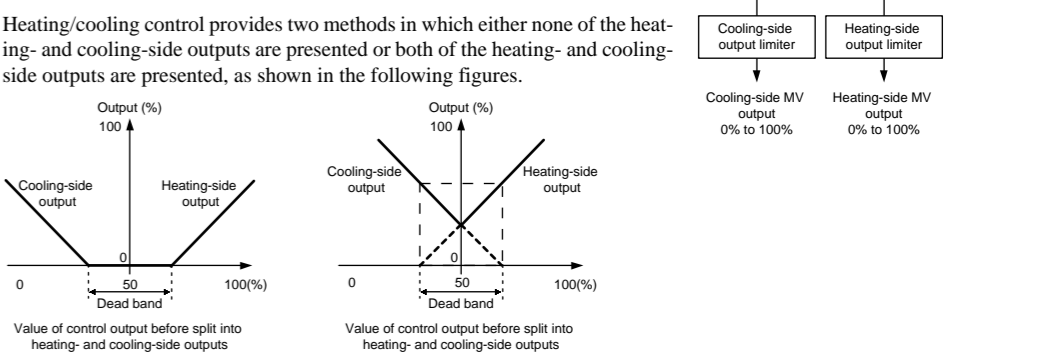
● Parameter-initializing Parameters

Located in: Main menu = **UTMD** (UTMD) ; Submenu = **INIT** (INIT)

Table with 6 columns: Parameter Symbol, Name of Parameter, Setting Range and Description, Initial Value, User Setting, Target Item in CD-ROM. Includes parameter ini.

■ Tips about Heating/Cooling Control (for heating/cooling controllers only)

In heating/cooling control, the controller outputs the result of computation after splitting it into heating-purpose and cooling-purpose signals. In addition, the controller can perform PID control or ON/OFF control on the heating and cooling sides separately.

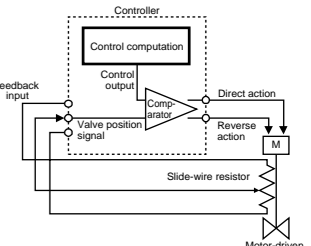


Precautions in Heating/Cooling Control


- Keep the ratio of the heating-side proportional band (P) to the cooling-side proportional band (Pc) equal to or below 5.
If neither the heating-side nor the cooling-side is performing ON/OFF control, setting the integral time (I or Ic) of one side to "0" results in the Integral Time parameters of both sides being set to "OFF", irrespective of the integral time setting of the other side.

■ Tips about Position Proportional Control (for position proportional controllers only)

Position proportional control can be of either feedback type or estimating type. In feedback-type position proportional control, the controller obtains a valve position signal from a feedback slide-wire resistor attached to a valve. In estimating-type position proportional control, you set the operating time required for a valve to change from the fully-closed position to the fully-open position beforehand.



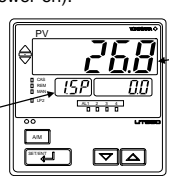

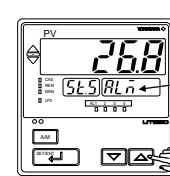

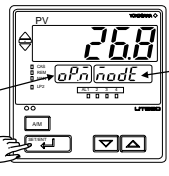

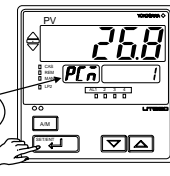




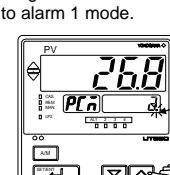

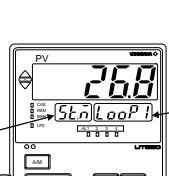

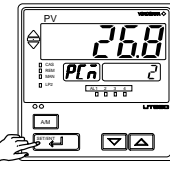

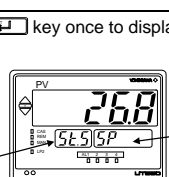

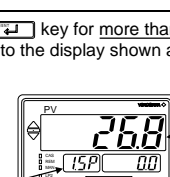
This manual describes the PV display color changing function "Active Color PV Display."

Carry out settings according to the following procedures after referring to "Functions of Active Color PV Display" on the back of this manual. Use Parameter Map User's Manual to understand the required parameters. If you cannot remember how to carry out an operation during setting, press the  key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on.

■ Setting the PV Display Color Changing Function "Active Color PV Display"

The following operating procedure describes an example of changing the PV color mode (factory-set default: "Fixed in red" mode) to "Link to alarm 1" mode.

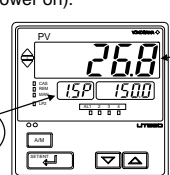

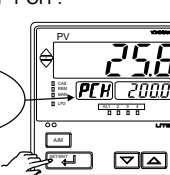

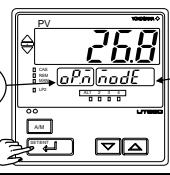


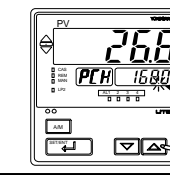

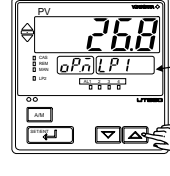

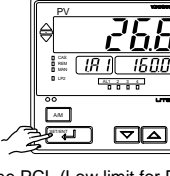

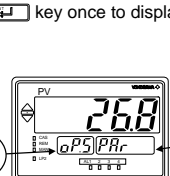

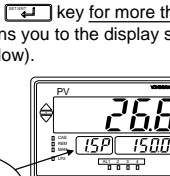
Parameter Symbol	Name of Parameter	Setting Range	Initial Value
PCL (PCM)	PV color mode	0 : Fixed in green 1 : Fixed in red 2 : Link to alarm 1 (Alarm OFF:green, Alarm ON: red) 3 : Link to alarm 1 (Alarm OFF:red, Alarm ON:green) 4 : Link to alarm 1 and 2 (Alarm OFF:green, Alarm ON:red) 5 : Link to alarm 1 and 2 (Alarm OFF:red, Alarm ON:green) 6 : PV limit (Within PV range:green, Out of range:red) 7 : PV limit (Within PV range:red, Out of range:green) 8 : SP deviation (Within deviation:green, Out of deviation:red) 9 : SP deviation (Within deviation:red, Out of deviation:green)	1

<p>1. Bring the operating display into view (display appears at power-on).</p>  <p>Displays PV.</p> <p>Displays target setpoint-1 "1.SP".</p>	<p>6. Press the  key once to display the submenu "ALM".</p>  <p>Displays submenu "ALM".</p>
<p>2. Press the  key for more than 3 seconds to call up the main menu "MODE".</p>  <p>Displays main menu "MODE".</p> <p>Displays symbol "OP.M".</p>	<p>7. Press the  key once to display the parameter "PCM" (PV color mode).</p>  <p>Displays parameter "PCM".</p>
<p>3. Press the  key once to display the main menu "STUP".</p>  <p>Displays main menu "STUP".</p>	<p>8. Press the  or  key to display the required setpoint. The figure below shows an example of setting Link to alarm 1 mode.</p>  <p>Blinks during change.</p>
<p>4. Press the  key once to display the main menu "LOOP1".</p>  <p>Displays main menu "LOOP1".</p> <p>Displays symbol "ST.M".</p>	<p>9. Press the  key once to register the setpoint.</p>  <p>If PCM=6,7,8 or 9, also set the relating parameters PCH (High limit for PV color change) and PCL (Low limit for PV color change).</p>
<p>5. Press the  key once to display the submenu "SP".</p>  <p>Displays submenu "SP".</p> <p>Displays symbol "ST.S".</p>	<p>10. Press the  key for more than 3 seconds. This returns you to the display shown at power-on (figure below).</p>  <p>Displays PV.</p> <p>Displays target setpoint-1 "1.SP".</p>

■ Setting the High Limit and Low Limit for PV Color Change

The following operating procedure describes an example of changing the PV display color by PV limit(s). Set the High limit and/or Low limit for PV color change.

Parameter Symbol	Name of Parameter	Setting Range	Initial Value
PCH (PCH)	High limit for PV color change	When PCM (PV color mode parameter) = 6 or 7: -100.0 to 100.0 % of PV input range.	When PCM = 6 or 7: PCH:100.0 %, PCL:0.0 %
PCL (PCL)	Low limit for PV color change	When PCM (PV color mode parameter) = 8 or 9: -100.0 to 100.0 % of PV input range span.	When PCM = 8 or 9: PCH and PCL:1.0 %

<p>1. Bring the operating display into view (display appears at power on).</p>  <p>Displays PV.</p> <p>Displays target setpoint-1 "1.SP".</p>	<p>5. Press the  key several times to display the parameter "PCH".</p>  <p>Displays parameter "PCH".</p>
<p>2. Press the  key for more than 3 seconds to call up the main menu "MODE".</p>  <p>Displays symbol "OP.M".</p> <p>Displays main menu "MODE".</p>	<p>6. Press the  or  key to display the required setpoint.</p>  <p>Blinks during change.</p>
<p>3. Press the  key once to display the main menu "LP1".</p>  <p>Displays main menu "LP1".</p>	<p>7. Press the  key once to register the setpoint.</p>  <p>Also set the PCL (Low limit for PV color change parameter) that follows this step.</p>
<p>4. Press the  key once to display the submenu "PAR".</p>  <p>Displays symbol "OP.S".</p> <p>Displays submenu "PAR".</p>	<p>8. Press the  key for more than 3 seconds. This returns you to the display shown at power-on (figure below).</p>  <p>Displays PV.</p> <p>Displays target setpoint-1 "1.SP".</p>

Functions of Active Color PV Display

This part describes the functions of "Active Color PV Display." PV display color is changed by the following four actions.

PV display color is selectable from red-to-green or green-to-red changing action, or fixed color.

- Link to alarm 1 mode (when PCM = 2, 3) (Setting example-1)

Link to alarm 1 and 2 mode (when PCM = 4, 5) is the same. When either of the alarms occurs, the display color is changed.

- SP deviation mode (when PCM = 8, 9) (Setting example-2)

- PV limit mode (when PCM = 6, 7) (Setting example-3)

- Fixed color mode (when PCM = 0, 1) (Setting example-4)

Setting Example-1 : Link to Alarm

Works linking to alarm 1.

Set "PV high limit alarm" for alarm-1 type, and "80°C" for alarm-1 setpoint.

If PCM (PV color mode parameter) = 2, PV display color is changed from green to red

when PV input value exceeds alarm-1 setpoint.

The red-to-green changing action is selectable.

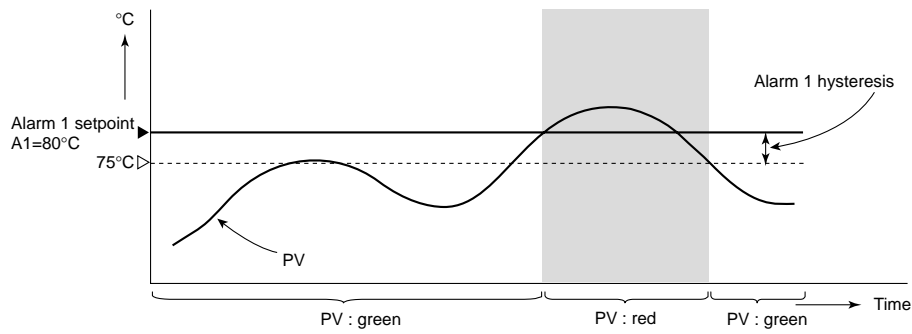
Setting parameters:

PCM (PV color mode parameter) = 2

AL1 (Alarm-1 type parameter) = 1

A1 (Alarm-1 setpoint parameter) = 80°C

HY1 (Alarm-1 hysteresis parameter) = 5°C



Setting Example-3 : Link to PV

Set the high limit "70°C" for PCH, and the low limit "20°C" for PCL.

PV display color is changed from green to red when PV input value is out of the range.

The red-to-green changing action is selectable.

Setting parameters:

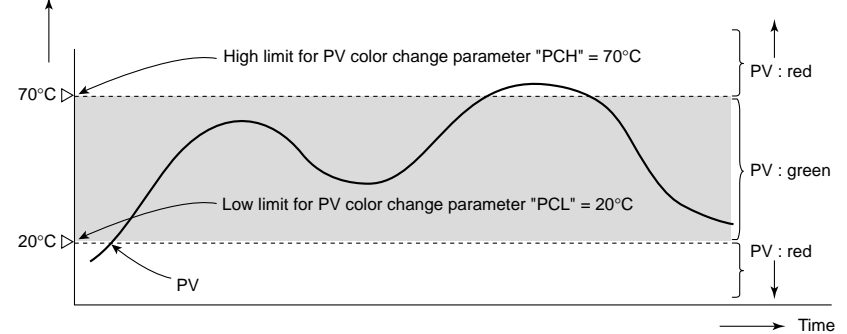
PCM (PV color mode parameter) = 6

PCH (High limit for PV color change parameter) = 70°C

PCL (Low limit for PV color change parameter) = 20°C

Hysteresis fixed to 0.25% is inserted where PV display color is changed.

In the example below, where changed from red to green.



Setting Example-2 : Change by Deviation

Set the high limit deviation band "10°C" for PCH and the low limit deviation band "5°C" for PCL,

for the current setpoint "50°C."

PV display color is changed from green to red when PV input value is out of the deviation.

The red-to-green changing action is selectable.

Setting parameters:

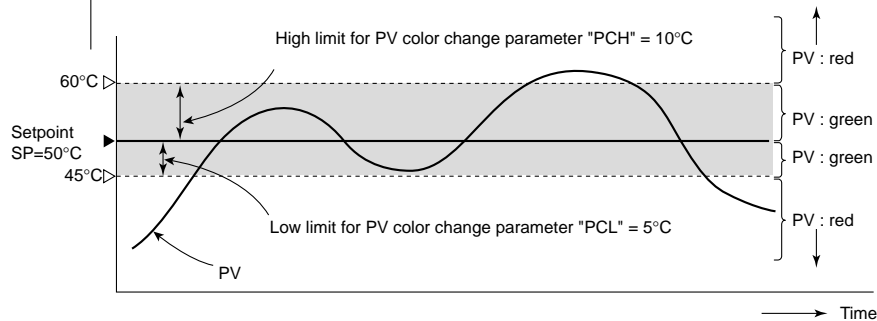
PCM (PV color mode parameter) = 8

PCH (High limit for PV color change parameter) = 10°C

PCL (Low limit for PV color change parameter) = 5°C

Hysteresis fixed to 0.25% is inserted where PV display color is changed.

In the example below, where changed from red to green.

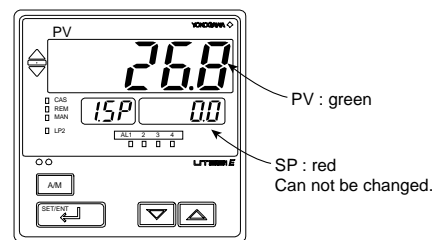


Setting Example-4 : Fixed in Red or Green

Fix the PV display color in green. Setting of Fixed in red mode is also possible.

Setting parameter :

PCM (PV color mode parameter) = 0



External RJC

The external RJC is not a compensation function built in a controller but a compensation function working outside the controller.

The external RJC is used when the input is thermocouple, and RJC=OFF.

Using external RJC makes the accuracy of RJC higher and shortens the compensating wire.

Parameter Symbol	Name of Parameter	Setting Range	Initial Value
ErJ (ERJ)	External RJC setpoint	-50.0 to 50.0°C, -58.0 to 122.0°F For thermocouple input, temperature compensation value outside the controller can be set. Available only when RJC=OFF.	0.0°C 32.0°F

